Section 5

Observational Studies 2

Sooahn Shin

GOV 2003

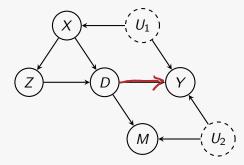
Oct 14, 2021

Overview

- Logistics:
 - Pset 5 released! Due at 11:59 pm (ET) on Oct 20
- Today's topics:
 - 1. Directd Acyclic Graphs

Motivation

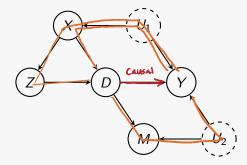
• Assume that you've come out with a DAG based on your expertise.



• Suppose you want to identify a causal effect of D on Y.

Motivation

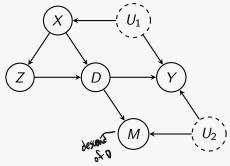
• Assume that you've come out with a DAG based on your expertise.



- Suppose you want to identify a causal effect of D on Y.
 - In a nutshell, what you might want to do is to block all the paths that yields statistical associations between *D* and *Y*.

Motivation

Assume that you've come out with a DAG based on your expertise.



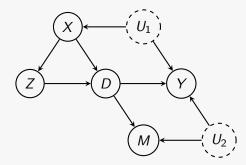
- Suppose you want to identify a causal effect of D on Y.
 - In a nutshell, what you might want to do is to block all the paths That yields statistical associations between D and Y. X, Z, M X, Y
 - Thus, you want to find a set of nodes **S** such that
 - once we condition on S, no unmeasured confounding holds and
 - any descend of D is not in $\mathbf{S} \sim \mathbf{no post-treatment bias}$.
- ~ Use backdoor criterion!

• Things we have to know to check the backdoor criterion:

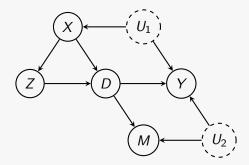
- Things we have to know to check the backdoor criterion:
 - Three common structures:
 - confounder (fork): $A \leftarrow C \rightarrow B$
 - collider (inverted fork): $A \rightarrow C \leftarrow B$
 - mediator (chain): $A \rightarrow C \rightarrow B$

- Things we have to know to check the backdoor criterion:
 - Three common structures:
 - confounder (fork): $A \leftarrow C \rightarrow B$
 - collider (inverted fork): $A \rightarrow C \leftarrow B$
 - mediator (chain): $A \rightarrow C \rightarrow B$
 - How to block a path between A and B
 - If $A \leftarrow C \rightarrow B$: condition on *C*.
 - If $A \rightarrow C \leftarrow B$: **do not** condition on *C*.
 - If $A \rightarrow C \rightarrow B$: condition on C.

- Things we have to know to check the backdoor criterion:
 - Three common structures:
 - confounder (fork): $A \leftarrow C \rightarrow B$
 - collider (inverted fork): $A \rightarrow C \leftarrow B$
 - mediator (chain): $A \rightarrow C \rightarrow B$
 - How to block a path between A and B
 - If $A \leftarrow C \rightarrow B$: condition on *C*.
 - If $A \rightarrow C \leftarrow B$: **do not** condition on *C*.
 - If $A \rightarrow C \rightarrow B$: condition on C.
 - **D**-separation: $A \perp B \mid C$
 - 1. Find all paths between A and B.
 - 2. Check if each path is **blocked**.
 - 3. If all paths are blocked, then A is **d-separated** from B by C

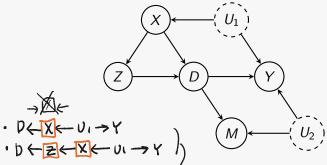


- 1. List all of the **backdoor** paths between D and Y.
 - · DEXEUISY
 - ・レイモイメーリーケ

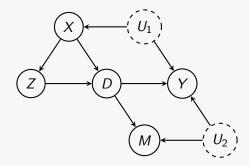


- 1. List all of the **backdoor** paths between D and Y.
- 2. List all the possible set of nodes **S** that you can condition on.

Ø 1×1 1≈1 3M2
 9×≈1 1×,M3 1≈,M1
 1×,æ,M3



- 1. List all of the **backdoor** paths between D and Y.
- 2. List all the possible set of nodes S that you can condition on.
- 3. List all the **S** such that **blocks** all the backdoor paths.

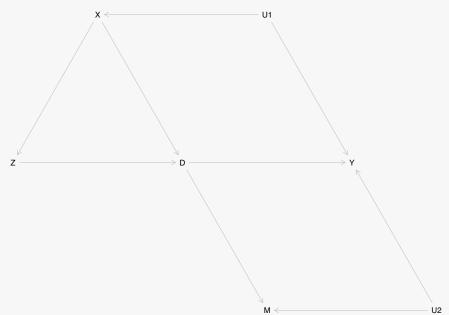


- 1. List all of the **backdoor** paths between D and Y.
- 2. List all the possible set of nodes **S** that you can condition on.
- 3. List all the **S** such that **blocks** all the backdoor paths.
- 4. Among those S, drop the sets which include a descend of D.

```
• DAGitty: www.dagitty.net
```

```
library(dagitty)
g <- dagitty('dag {</pre>
    X [pos="1,-1.5"]
    Y [pos="4,0"]
    Z [pos="0,0"]
    M [pos="3,1.5"]
    D [pos="2,0"]
    U1 [pos="3,-1.5"]
    U2 [pos="5,1.5"]
    X -> Z -> D -> Y
    X -> D -> M
    M <- U2 -> Y
    X <- U1 -> Y
1')
latents(g) <- c("U1", "U2")
```





7

parents(g, "D") ## [1] "X" "Z" ancestors(g, "D") ## [1] "D" "Z" "X" "U1" children(g, "D") ## [1] "M" "Y" descendants(g, "D") ## [1] "D" "Y" "M"

```
paths(g, "D", "Y")$paths
## [1] "D -> M <- U2 -> Y" "D -> Y" "D <- X <- U1 -> Y
## [4] "D <- Z <- X <- U1 -> Y"
paths(g, "D", "Y", directed = TRUE)$paths # only causal path(s)
## [1] "D -> Y"
```

```
dseparated(g, "Z", "D", c("X")) # because of Z -> D
```

[1] FALSE

dseparated(g, "Z", "M", c("D"))

[1] TRUE
impliedConditionalIndependencies(g)
latent(3) (U)

Xi, Xe

M _||_ X | D ## M _||_ Z | D ## Y _||_ Z | D, X

```
dseparated(g, "Z", "D", c("X")) # because of Z -> D
```

[1] FALSE

```
dseparated(g, "Z", "M", c("D"))
```

[1] TRUE

impliedConditionalIndependencies(g)

M _||_ X | D ## M _||_ Z | D ## Y _||_ Z | D, X

adjustmentSets(g, "D", "Y", type="minimal")

{ X }

Caveat: adjustmentSets may include unobserved variables
which we cannot actually condition on.
S = adjustmentSets(g, "D", "Y", type="all")
S[!grepl("U1|U2", S)]
{ X, Z }
Note that this implements a slightly more general criterion

(sometimes it may contain descendants)

$$p(Y(d)) = \sum_{M} p(M_2 = m|T_1 = t)$$

$$= \sum_{M} p(Y(d) = \sum_{M} p(M_2 = m|T_1 = t)$$

$$= \sum_{M} p(Y(d) = m|T_1 = t) p(T_1 = t) p(T_2 = t) p(T_1 = t) p(T_2 = t)$$