

* slides are uploaded on
the website - materials!

Section 5

Observational Studies 1

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GOV 2003

Oct 7, 2021

Overview

- Logistics:
 - **No pset this week!**
- Today's topics:
 1. Review session
 2. No unmeasured confounding + regression

What we have learned so far?

- Fisher's approach to inference: randomization inference
- Neyman's approach to inference for the ATE: diff-in-means estimator

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- Fisher's approach to inference: randomization inference
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$$\hat{\tau}_{diff} \rightarrow V(\hat{\tau}) \rightarrow \hat{V}(\hat{\tau})$$
- Analyzing experiments with regression
 - Simple OLS estimator + robust variance estimator
 - + Covariates
 - + Block design
 - + Cluster design

* unbiased
consistent
asym. norm.

variance estimator

 - conservative = positive bias
 - efficient = small var

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- This week: observational studies
 - Before we move on, let's quickly review experimental designs!

Experimental design

- Types of experiments by their assignment mechanism
 - **Bernoulli randomization:** Each unit is assigned $D_i = 1$ with prob. p independently (coin flips)
 - **Completely randomized experiment:** Randomly sample n_1 units from the population to be treated
 - **Block/stratified randomized experiment:** Completely randomized experiment in each block \leadsto always efficient for PATE
 - **Cluster randomized experiment:** Treatment assignment at a higher level \leadsto allows for interference within clusters

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- Exercise: comparing experimental designs through simulation
 1. Assume true potential outcomes
 2. Select one assignment mechanism
 3. Randomly generate treatment assignment
 4. Estimate SATE (using diff-in-means estimator)
 5. Repeat 3-4 multiple times
 6. Draw a distribution of estimates

Experimental design

- Setup:
 - $\text{SATE} = \frac{1}{16} \sum_{i=1}^{16} \tau_i = 8.5$
 - Design is balanced (except for Bernoulli)

Unit	$Y_i(0)$	$Y_i(1)$	τ_i	Block/Cluster
1	0	1	1	A
2	0	2	2	A
3	0	3	3	A
4	0	4	4	A
5	0	5	5	B
\vdots	\vdots	\vdots	\vdots	\vdots
16	0	16	16	D

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- Q: Which design would have the largest (smallest) variance?
- Check the results here: <https://twitter.com/aecoppock/status/1442545254423486465?s=21>

Observational studies

- Problem:

- Non-randomized treatment
- $\leadsto \{Y_i(1), Y_i(0)\} \not\perp D_i$
- \leadsto selection bias = unidentified ATT

$$\underbrace{\mathbb{E}[Y_i|D_i = 1] - \mathbb{E}[Y_i|D_i = 0]}_{\text{diff-in-means}} = \underbrace{\tau_t}_{\substack{\text{ATT} \\ \text{Q consistency}}} + \underbrace{\mathbb{E}[Y_i(0)|D_i = 1] - \mathbb{E}[Y_i(0)|D_i = 0]}_{\text{selection bias}}$$

$$\tau_t + \mathbb{E}[Y_i(0)|D_i = 1] - \mathbb{E}[Y_i(0)|D_i = 0]$$

Observational studies

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- What can we do for the **identification**?
 - Assume no unmeasured confounding with positivity
 - Partial identification: analysis of bounds for the ATE
 - Sensitivity analysis ...

Identification: No unmeasured confounding

- Identification

- Let's begin with most common set of assumptions:

1. **Overlap/Positivity:** $0 < \Pr[D_i = 1 | \mathbf{X}_i] < 1$
2. **No unmeasured confounding:** $\{Y_i(1), Y_i(0)\} \perp\!\!\!\perp D_i \mid \mathbf{X}_i$



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 - This will identify the PATE:

$$\begin{aligned}\tau &= \mathbb{E}[Y_i(1) - Y_i(0)] \\&= \mathbb{E}_{\mathbf{X}} \{E[Y_i(1) - Y_i(0) \mid \mathbf{X}_i]\} \quad \text{iter.} \\&= \mathbb{E}_{\mathbf{X}} \{E[Y_i(1) \mid \mathbf{X}_i] - E[Y_i(0) \mid \mathbf{X}_i]\} \quad \text{linear.} \\&= \mathbb{E}_{\mathbf{X}} \{E[Y_i(1) \mid D_i = 1, \mathbf{X}_i] - E[Y_i(0) \mid D_i = 0, \mathbf{X}_i]\} \quad \swarrow \text{n. u. c.} \\&= \mathbb{E}_{\mathbf{X}} \{E[Y_i \mid D_i = 1, \mathbf{X}_i] - E[Y_i \mid D_i = 0, \mathbf{X}_i]\} \quad \swarrow \text{consistency.}\end{aligned}$$

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- Estimation
 - Regression
 - Matching/Weighting (Module 7)

Estimation: Regression-based estimators

- Treated and control conditional expectation functions (CEFs):

$$\mu_1(\mathbf{x}) = \mathbb{E}[Y_i(1) \mid \mathbf{X}_i = \mathbf{x}], \quad \mu_0(\mathbf{x}) = \mathbb{E}[Y_i(0) \mid \mathbf{X}_i = \mathbf{x}]$$

- By consistency and no unmeasured confounding:

$$\underbrace{\mu_1(\mathbf{x})}_{\text{counterfactual}} = \underbrace{\mathbb{E}[Y_i \mid D_i = 1, \mathbf{X}_i = \mathbf{x}]}_{\text{observational}}, \quad \mu_0(\mathbf{x}) = \mathbb{E}[Y_i \mid D_i = 0, \mathbf{X}_i = \mathbf{x}]$$

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- Estimate CEFs using regression estimators $\hat{\mu}_1(\mathbf{x})$ and $\hat{\mu}_0(\mathbf{x})$.
 - Might be linear or nonlinear models (e.g., GAMs)
 - \leadsto Regression estimator of the ATE:

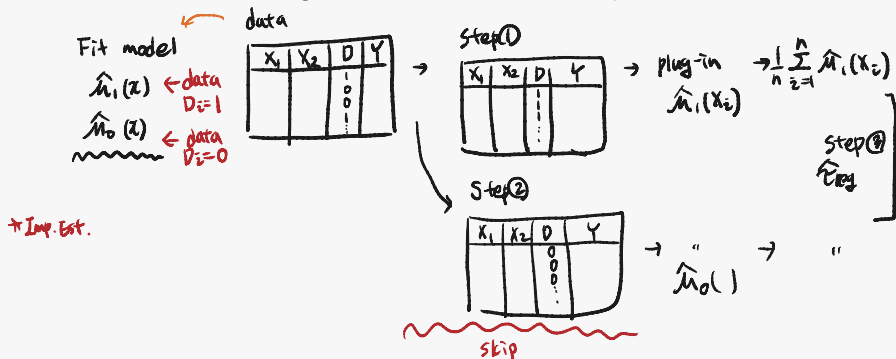
$$\hat{\tau}_{\text{reg}} = \frac{1}{n} \sum_{i=1}^n \hat{\mu}_1(\mathbf{X}_i) - \hat{\mu}_0(\mathbf{X}_i)$$

Estimation: Regression-based estimators

$$\hat{\tau}_{\text{reg}} = \frac{1}{n} \sum_{i=1}^n \hat{\mu}_1(\mathbf{X}_i) - \hat{\mu}_0(\mathbf{X}_i)$$

- General procedure:

- ① Obtain predicted values for all units when $D_i = 1$.
- ② Obtain predicted values for all units when $D_i = 0$.
- ③ Take the average difference between these predicted values.



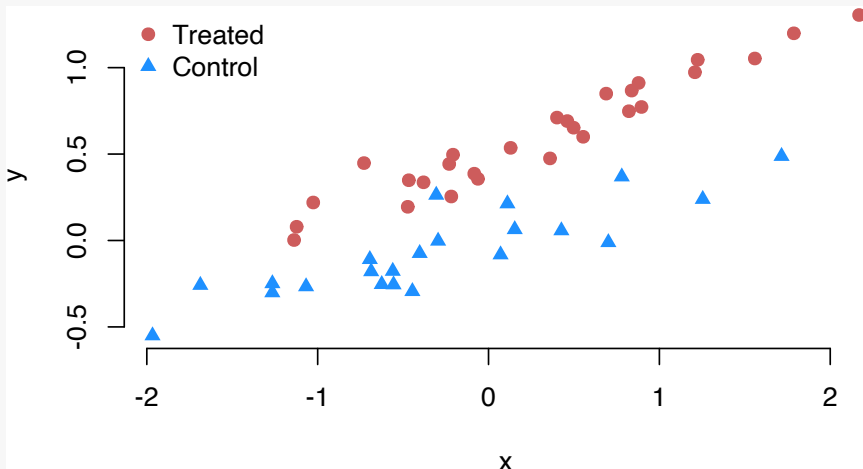
Estimation: Regression-based estimators

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- General procedure:
 - Obtain predicted values for all units when $D_i = 1$.
 - Obtain predicted values for all units when $D_i = 0$.
 - Take the average difference between these predicted values.
- Safest practice:
 - Estimate separate regression in each treatment group.
 - Sometimes called an imputation estimator.
 - Procedure:
 - Regress Y_i on X_i in the treatment group and get predicted values for all units (treated or control).
 - Regress Y_i on X_i in the control group and get predicted values for all units (treated or control).
 - Take the average difference between these predicted values.

Toy example

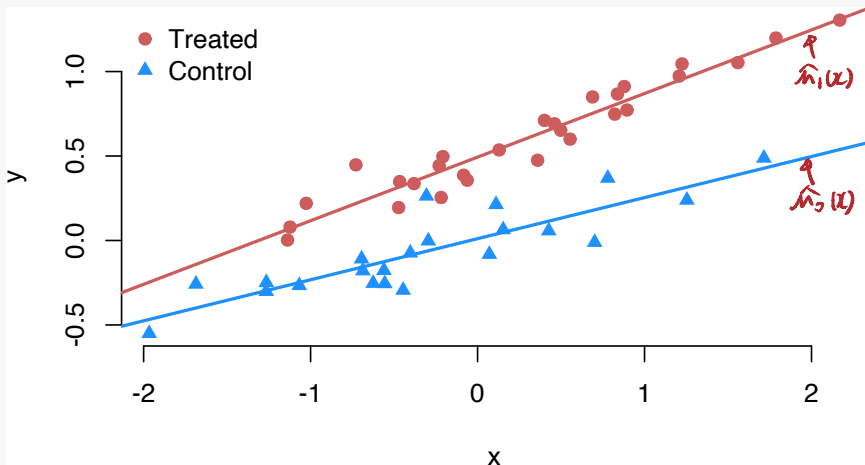
- Data is as follows and we will use linear regression to estimate CEFs



Imputation estimator visualization

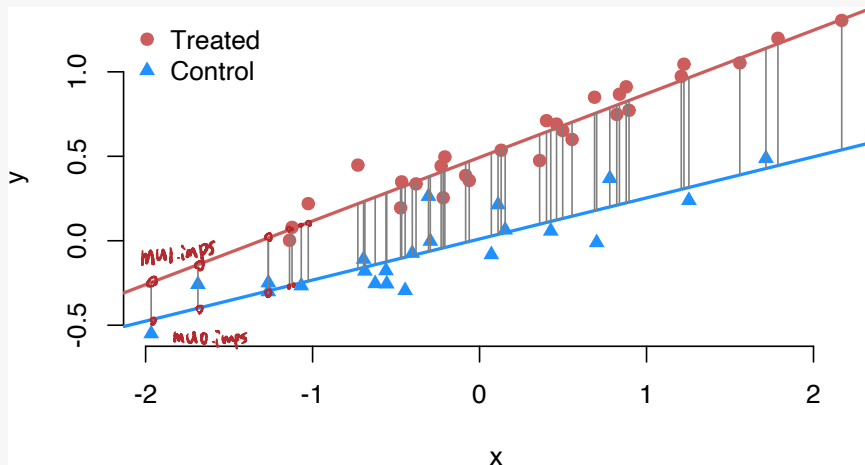
\hat{m}_1 mod0 <- `lm(y~x, data = toy_data, subset = d==0)` ← control group
 \hat{m}_0 mod1 <- `lm(y~x, data = toy_data, subset = d==1)` ← treated

$Y \perp\!\!\!\perp d \mid X$
ident.



```
mu0imps = predict(mod0, toy_data); mu1imps = predict(mod1, toy_data)
cat("Estimate of ATE:", mean(mu1imps - mu0imps))
```

```
## Estimate of ATE: 0.4873975
```



Fully interacted OLS visualization

- What if $\hat{\mu}_1(\mathbf{x})$ and $\hat{\mu}_0(\mathbf{x})$ are from fully interacted OLS with centered covariates?
 - Equivalent to running separate models for $\hat{\mu}_1(\mathbf{x})$ and $\hat{\mu}_0(\mathbf{x})$
 - $\hat{\tau}_{\text{reg}} \equiv$ estimated coefficient on D_i
 - Recall: Under linear models, $\hat{\tau}_{\text{reg}}$ is **sometimes** equivalent to a coefficient.

$$Y_i = \alpha + \tau D_i + \tilde{X}_i \beta + \tilde{X}_i D_i \delta$$

$$\hat{\mu}_1(x_i) = (\hat{\alpha} + \hat{\tau}) + \tilde{X}_i (\hat{\beta} + \hat{\delta})$$

$$\hat{\mu}_0(x_i) = \hat{\alpha} + \tilde{X}_i \hat{\beta}$$

$$= \frac{1}{n} \sum_{i=1}^n \hat{\mu}_1(x_i) - \hat{\mu}_0(x_i)$$

$$(\hat{\alpha}, \hat{\tau}, \hat{\beta}, \hat{\delta}) = \arg \min_{(\alpha, \tau, \beta, \delta)} \sum_i (Y_i - \alpha - \tau D_i - \tilde{X}_i \beta - \tilde{X}_i D_i \delta)^2$$

$$\hat{\tau}_{\text{reg}} = \frac{1}{n} \sum_{i=1}^n (\hat{\tau} + \tilde{X}_i \hat{\delta})$$

$$\frac{1}{n} \sum_{i=1}^n \tilde{X}_i = 0$$

$$= \frac{1}{n} \sum_{i=1}^n \hat{\tau} = \hat{\tau}$$

$$= \arg \min_{(\alpha, \tau, \beta)} \sum_{i: D_i=0} (Y_i - \alpha - \tilde{X}_i \beta)^2 + \sum_{i: D_i=1} (Y_i - (\alpha + \tau) - \tilde{X}_i (\beta + \delta))^2$$

$\downarrow \alpha'$
 $\downarrow \beta'$

$$= \arg \min_{(\alpha, \beta)} \sum_{i: D_i=0} \text{''} + \arg \min_{(\alpha', \beta')} \sum_{i: D_i=1} \text{''}$$

Fully interacted OLS visualization

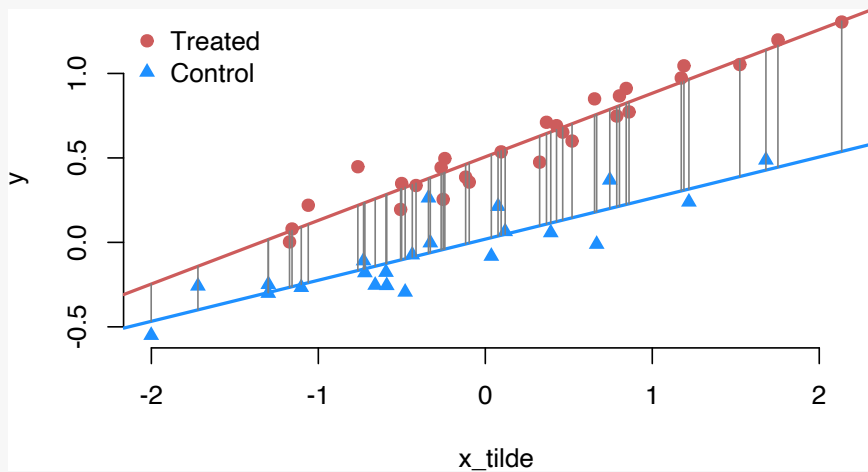
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```
toy_data$x_tilde <- toy_data$x - mean(toy_data$x)
mod_full <- lm(y~d+x_tilde+d*x_tilde, data = toy_data)
dat0 <- toy_data %>% mutate(d = 0); dat1 <- toy_data %>% mutate(d = 1)
mu0.full = predict(mod_full, dat0); mu1.full = predict(mod_full, dat1)
cat("Estimate of ATE (Fully interacted):", mean(mu1.full - mu0.full),
    "\nEstimate of ATE (Imputation):", mean(mu1.imps - mu0.imps),
    "\nEstimated coefficient on Di", mod_full$coefficients["d"])
```

```
## Estimate of ATE (Fully interacted): 0.4873975
```

```
## Estimate of ATE (Imputation): 0.4873975
```

```
## Estimated coefficient on Di 0.4873975
```



Uninteracted OLS visualization

- What if $\widehat{\mu}_1(\mathbf{x})$ and $\widehat{\mu}_0(\mathbf{x})$ are from the same OLS model $Y \sim D + X$?
 - $\widehat{\tau}_{\text{reg}} \equiv$ estimated coefficient on D_i

Uninteracted OLS visualization

- What if $\hat{\mu}_1(\mathbf{x})$ and $\hat{\mu}_0(\mathbf{x})$ are from the same OLS model $Y \sim D + X$?

- $\hat{\tau}_{reg} \equiv$ estimated coefficient on D_i

$$Y_i = \hat{\tau} D_i + X_i' \beta + \epsilon_i$$

$$\hat{\mu}_1(\mathbf{x}) = \hat{\tau} + X_i' \hat{\beta}$$

$$\hat{\mu}_0(\mathbf{x}) = X_i' \hat{\beta}$$

```
mod <- lm(y~d+x, data = toy_data)
```

```
mu0 = predict(mod, dat0); mu1 = predict(mod, dat1)
```

```
cat("Estimate of ATE (Uninteracted):", mean(mu1 - mu0),  
    "\nEstimated coefficient on Di", mod$coefficients["d"],  
    "\nEstimate of ATE (Fully interacted):", mean(mu1.full - mu0.full),  
    "\nEstimate of ATE (Imputation):", mean(mu1.imps - mu0.imps))
```

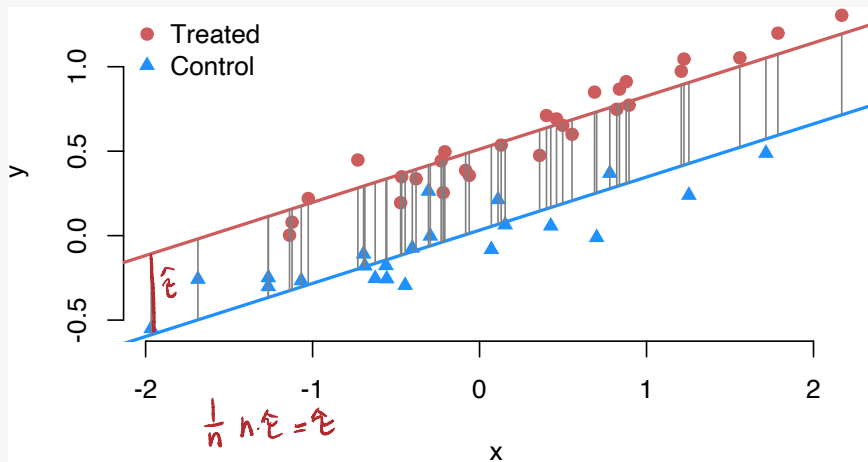
```
## Estimate of ATE (Uninteracted): 0.479676
```

```
## Estimated coefficient on Di 0.479676
```

```
## Estimate of ATE (Fully interacted): 0.4873975
```

```
## Estimate of ATE (Imputation): 0.4873975
```

$$\begin{aligned} \hat{\tau}_{reg} &= \frac{1}{n} \sum_{i=1}^n \hat{\mu}_1(X_i) - \hat{\mu}_0(X_i) \\ &= \frac{1}{n} \sum_{i=1}^n \hat{\tau} \\ &= \frac{1}{n} \cdot n \hat{\tau} \\ &= \underline{\hat{\tau}} \end{aligned}$$



Variance estimation

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Variance estimation

- How do we get estimates of the variance of $\hat{\tau}_{\text{reg}}$?
- **Nonparametric bootstrap**
 - Recall: Source of variance is due to **sampling**
 - Idea: View sample (data) as “population” → in-sample “sampling”

$$\begin{aligned} F &\rightarrow \underbrace{\text{data}} \rightarrow \hat{\theta} \\ \hat{F}_n &\rightarrow \text{data}_{(s)} \rightarrow \hat{\theta}_{(s)} \end{aligned}$$

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- **Nonparametric bootstrap**
 - Recall: Source of variance is due to **sampling**
 - Idea: View sample (data) as “population” → in-sample “sampling”
- Procedure:
 - Randomly resample n rows of the data with replacement
 - Refit the regressions on the bootstrapped data.
 - Calculate $\hat{\tau}_{\text{reg}}$ in each bootstrap
 - Repeat several times and use empirical variance of the bootstraps

Bootstrap sample codes

```
set.seed(02138); sims<-500; tau_hat_draws<-rep(NA, sims)
for (i in 1:sims) { # Repeat the following several times
  # 1. Randomly resample n rows of the data with replacement
  sample_boot <- dplyr::slice_sample(toy_data, n = nrow(toy_data),
                                     replace = TRUE)

  # 2. Refit the regressions on the bootstrapped data
  model <- lm(y ~ d + x_tilde + d*x_tilde, data = toy_data)
  dat1 <- sample_boot; dat1$d <- 1
  dat0 <- sample_boot; dat0$d <- 0
  mu1_hat <- predict(model, newdata = dat1)
  mu0_hat <- predict(model, newdata = dat0)
  # 3. Calculate tau_hat in each bootstrap
  tau_hat_draws[i] <- mean(mu1_hat - mu0_hat)
}

# 4. Use empirical variance of the bootstraps
var(tau_hat_draws)

## [1] 0.0003247686
```

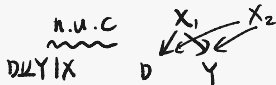
DAG

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 - One way: use DAGs and look at back-door paths.

DAG

- How do we know if no unmeasured confounders holds?
 - One way: use DAGs and look at back-door paths.
- **D-separation**
 - Can we determine conditional independence from our causal DAG?
 - Yes! To verify that $A \perp\!\!\!\perp B \mid C$ where each is a set of nodes:
 1. Find all paths between A and B .
 2. Check if each path is **blocked**.
 3. If all paths are blocked, then A is **d-separated** from B by C

DAG



- How do we know if no unmeasured confounders holds?

- One way: use DAGs and look at back-door paths.

D-separation

$D \leftarrow$

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- Yes! To verify that $A \perp\!\!\!\perp B \mid C$ where each is a set of nodes:

- Find all paths between A and B .
- Check if each path is **blocked**. $\stackrel{\text{independence}}{=}$
- If all paths are blocked, then A is **d-separated** from B by C

- Ways to block $A \rightarrow B$ (each is a node):

1. $A \rightarrow C \rightarrow B$, C is observed (conditioned)

2. $A \leftarrow C \leftarrow B$, C is observed

3. $A \leftarrow C \rightarrow B$, C is observed

4. $A \rightarrow C \leftarrow B$, C is **not** observed

- If C observed \leadsto collider bias

- e.g., A =bicycle accident, B =stomachache, C =hospitalization;
Sackett (1979)

$A \perp\!\!\!\perp B \mid C$
"
"
 $A \not\perp\!\!\!\perp B \mid C$

mediator

confounder