Module 9: Panel Data

Fall 2021

Matthew Blackwell

Gov 2003 (Harvard)

• Where we have found good controls:

- Where we have found good controls:
 - · Units randomized to receive control

- Where we have found good controls:
 - · Units randomized to receive control
 - Units with similar values of covariates

- Where we have found good controls:
 - · Units randomized to receive control
 - Units with similar values of covariates
 - Units with opposite value of some instrument

- Where we have found good controls:
 - Units randomized to receive control
 - Units with similar values of covariates
 - Units with opposite value of some instrument
 - At a discontinuity in treatment assignment

- Where we have found good controls:
 - Units randomized to receive control
 - Units with similar values of covariates
 - Units with opposite value of some instrument
 - · At a discontinuity in treatment assignment
- What if we have repeated measurements of the same units?

- Where we have found good controls:
 - Units randomized to receive control
 - Units with similar values of covariates
 - · Units with opposite value of some instrument
 - · At a discontinuity in treatment assignment
- What if we have repeated measurements of the same units?
- Now there are two possible sources of variation to exploit:

- Where we have found good controls:
 - Units randomized to receive control
 - Units with similar values of covariates
 - · Units with opposite value of some instrument
 - At a discontinuity in treatment assignment
- What if we have repeated measurements of the same units?
- Now there are two possible sources of variation to exploit:
 - Exploit cross-sectional variation in treatment.

- Where we have found good controls:
 - Units randomized to receive control
 - Units with similar values of covariates
 - · Units with opposite value of some instrument
 - At a discontinuity in treatment assignment
- What if we have repeated measurements of the same units?
- Now there are two possible sources of variation to exploit:
 - Exploit **cross-sectional** variation in treatment.
 - Exploit variation in treatment within a unit over time (before/after)

Cross-sectional vs before/after



1/ Difference in differences

• Does increasing the minimum wage affect employment?

- Does increasing the minimum wage affect employment?
- Classical economic theory tends to point to negative effects.

- Does increasing the minimum wage affect employment?
- Classical economic theory tends to point to negative effects.
- But difficult to randomize changes to the minimum wage.

- Does increasing the minimum wage affect employment?
- Classical economic theory tends to point to negative effects.
- But difficult to randomize changes to the minimum wage.
- In 1992, NJ minimum wage increased from \$4.25 to \$5.05

- Does increasing the minimum wage affect employment?
- Classical economic theory tends to point to negative effects.
- But difficult to randomize changes to the minimum wage.
- In 1992, NJ minimum wage increased from \$4.25 to \$5.05
 - Neighboring PA stays at \$4.25

- Does increasing the minimum wage affect employment?
- Classical economic theory tends to point to negative effects.
- But difficult to randomize changes to the minimum wage.
- In 1992, NJ minimum wage increased from \$4.25 to \$5.05
 - Neighboring PA stays at \$4.25
 - We observe employment in both states before and after increase

- Does increasing the minimum wage affect employment?
- Classical economic theory tends to point to negative effects.
- But difficult to randomize changes to the minimum wage.
- In 1992, NJ minimum wage increased from \$4.25 to \$5.05
 - Neighboring PA stays at \$4.25
 - We observe employment in both states before and after increase
- Look at eastern PA and NJ fast food restaurants.

- Does increasing the minimum wage affect employment?
- Classical economic theory tends to point to negative effects.
- But difficult to randomize changes to the minimum wage.
- In 1992, NJ minimum wage increased from \$4.25 to \$5.05
 - Neighboring PA stays at \$4.25
 - We observe employment in both states before and after increase
- Look at eastern PA and NJ fast food restaurants.
 - Similar prices, wages, products, etc.

- Does increasing the minimum wage affect employment?
- Classical economic theory tends to point to negative effects.
- But difficult to randomize changes to the minimum wage.
- In 1992, NJ minimum wage increased from \$4.25 to \$5.05
 - Neighboring PA stays at \$4.25
 - We observe employment in both states before and after increase
- Look at eastern PA and NJ fast food restaurants.
 - Similar prices, wages, products, etc.
 - Most likely to be affected by the change.

• Basic setup: two groups, two time periods.

- Basic setup: two groups, two time periods.
 - Pre-period (t = 0): neither group is treated.

- Basic setup: two groups, two time periods.
 - Pre-period (t = 0): neither group is treated.
 - Post-period (t = 1): one group is treated, other remains untreated.

- Basic setup: two groups, two time periods.
 - Pre-period (t = 0): neither group is treated.
 - Post-period (t = 1): one group is treated, other remains untreated.
- Groups defined by treatment status in post-period:

- Basic setup: two groups, two time periods.
 - Pre-period (t = 0): neither group is treated.
 - Post-period (t = 1): one group is treated, other remains untreated.
- Groups defined by treatment status in post-period:
 - $G_i = 1$ are those that are treated at t = 1

- Basic setup: two groups, two time periods.
 - Pre-period (t = 0): neither group is treated.
 - Post-period (t = 1): one group is treated, other remains untreated.
- Groups defined by treatment status in post-period:
 - $G_i = 1$ are those that are treated at t = 1
 - $G_i = 0$ for those that are always untreated

- Basic setup: two groups, two time periods.
 - Pre-period (t = 0): neither group is treated.
 - Post-period (t = 1): one group is treated, other remains untreated.
- Groups defined by treatment status in post-period:
 - $G_i = 1$ are those that are treated at t = 1
 - $G_i = 0$ for those that are always untreated
- Treatment status in each period:

- Basic setup: two groups, two time periods.
 - Pre-period (t = 0): neither group is treated.
 - Post-period (t = 1): one group is treated, other remains untreated.
- Groups defined by treatment status in post-period:
 - $G_i = 1$ are those that are treated at t = 1
 - $G_i = 0$ for those that are always untreated
- Treatment status in each period:
 - No treatment in the first period for either group: $D_{i0} = 0$

- Basic setup: two groups, two time periods.
 - Pre-period (t = 0): neither group is treated.
 - Post-period (t = 1): one group is treated, other remains untreated.
- Groups defined by treatment status in post-period:
 - $G_i = 1$ are those that are treated at t = 1
 - $G_i = 0$ for those that are always untreated
- Treatment status in each period:
 - No treatment in the first period for either group: $D_{i0} = 0$
 - In treated group, $G_i = 1 \rightsquigarrow D_{i1} = 1$

- Basic setup: two groups, two time periods.
 - Pre-period (t = 0): neither group is treated.
 - Post-period (t = 1): one group is treated, other remains untreated.
- Groups defined by treatment status in post-period:
 - $G_i = 1$ are those that are treated at t = 1
 - $G_i = 0$ for those that are always untreated
- Treatment status in each period:
 - No treatment in the first period for either group: $D_{i0} = 0$
 - In treated group, $G_i = 1 \rightsquigarrow D_{i1} = 1$
 - In control group, $G_i = 0 \rightsquigarrow D_{i1} = 0$

- Basic setup: two groups, two time periods.
 - Pre-period (t = 0): neither group is treated.
 - Post-period (t = 1): one group is treated, other remains untreated.
- Groups defined by treatment status in post-period:
 - $G_i = 1$ are those that are treated at t = 1
 - $G_i = 0$ for those that are always untreated
- Treatment status in each period:
 - No treatment in the first period for either group: $D_{i0} = 0$
 - In treated group, $G_i = 1 \rightsquigarrow D_{i1} = 1$
 - In control group, $G_i = 0 \rightsquigarrow D_{i1} = 0$

Time periodPre-period (t = 0)Post-period (t = 1)Control group $(G_i = 0)$ $D_{i0} = 0$ $D_{i1} = 0$ Treated group $(G_i = 1)$ $D_{i0} = 0$ $D_{i1} = 1$

• $Y_{it}(d)$ is the potential outcome under treatment d at time t.

- $Y_{it}(d)$ is the potential outcome under treatment d at time t.
- Again, the individual causal effect is just $Y_{it}(1) Y_{it}(0)$.

- $Y_{it}(d)$ is the potential outcome under treatment d at time t.
- Again, the individual causal effect is just $Y_{it}(1) Y_{it}(0)$.
- Consistency: $Y_{it} = D_{it}Y_{it}(1) + (1 D_{it})Y_{it}(0)$

- $Y_{it}(d)$ is the potential outcome under treatment d at time t.
- Again, the individual causal effect is just $Y_{it}(1) Y_{it}(0)$.
- Consistency: $Y_{it} = D_{it}Y_{it}(1) + (1 D_{it})Y_{it}(0)$
 - Observe control p.o. for all units in first period: $Y_{i0}(0) = Y_{i0}$
- $Y_{it}(d)$ is the potential outcome under treatment d at time t.
- Again, the individual causal effect is just $Y_{it}(1) Y_{it}(0)$.
- Consistency: $Y_{it} = D_{it}Y_{it}(1) + (1 D_{it})Y_{it}(0)$
 - Observe control p.o. for all units in first period: $Y_{i0}(0) = Y_{i0}$
 - In treated group: $G_i = 1 \rightsquigarrow Y_{i1} = Y_{i1}(1)$

- $Y_{it}(d)$ is the potential outcome under treatment d at time t.
- Again, the individual causal effect is just $Y_{it}(1) Y_{it}(0)$.
- Consistency: $Y_{it} = D_{it}Y_{it}(1) + (1 D_{it})Y_{it}(0)$
 - Observe control p.o. for all units in first period: $Y_{i0}(0) = Y_{i0}$
 - In treated group: $G_i = 1 \rightsquigarrow Y_{i1} = Y_{i1}(1)$
 - In control group: $G_i = 0 \rightsquigarrow Y_{i1} = Y_{i1}(0)$

$$\tau_{ATT} = \mathbb{E}[Y_{i1}(1) - Y_{i1}(0)|G_i = 1]$$

$$\begin{aligned} \tau_{ATT} &= \mathbb{E}[Y_{i1}(1) - Y_{i1}(0)|G_i = 1] \\ &= \mathbb{E}[Y_{i1}(1)|G_i = 1] - \mathbb{E}[Y_{i1}(0)|G_i = 1] \end{aligned}$$

$$\begin{aligned} r_{ATT} &= \mathbb{E}[Y_{i1}(1) - Y_{i1}(0)|G_i = 1] \\ &= \mathbb{E}[Y_{i1}(1)|G_i = 1] - \mathbb{E}[Y_{i1}(0)|G_i = 1] \\ &= \underbrace{\mathbb{E}[Y_{i1}|G_i = 1]}_{(a)} - \underbrace{\mathbb{E}[Y_{i1}(0)|G_i = 1]}_{(b)} \end{aligned}$$

$$\begin{aligned} \tau_{ATT} &= \mathbb{E}[Y_{i1}(1) - Y_{i1}(0)|G_i = 1] \\ &= \mathbb{E}[Y_{i1}(1)|G_i = 1] - \mathbb{E}[Y_{i1}(0)|G_i = 1] \\ &= \underbrace{\mathbb{E}[Y_{i1}|G_i = 1]}_{(a)} - \underbrace{\mathbb{E}[Y_{i1}(0)|G_i = 1]}_{(b)} \end{aligned}$$

- Part (a) is just a conditional average of observed data \rightsquigarrow identified.

$$\begin{aligned} \tau_{ATT} &= \mathbb{E}[Y_{i1}(1) - Y_{i1}(0)|G_i = 1] \\ &= \mathbb{E}[Y_{i1}(1)|G_i = 1] - \mathbb{E}[Y_{i1}(0)|G_i = 1] \\ &= \underbrace{\mathbb{E}[Y_{i1}|G_i = 1]}_{(a)} - \underbrace{\mathbb{E}[Y_{i1}(0)|G_i = 1]}_{(b)} \end{aligned}$$

- Part (a) is just a conditional average of observed data \rightsquigarrow identified.
- Part (b) is a counterfactual: what would the average outcome in the treated group have been if it have been in control?

$$\tau_{ATT} = \mathbb{E}[Y_{i1}(1)|G_i = 1] - \mathbb{E}[Y_{i1}(0)|G_i = 1]$$

	Time period	
	Pre-period $(t = 0)$	Post-period $(t = 1)$
Control group $(G_i = 0)$	$\mathbb{E}[Y_{i0}(0) G_i=0]$	$\mathbb{E}[Y_{i1}(0) G_i=0]$
Treated group $(G_i = 1)$	$\mathbb{E}[Y_{i0}(0) G_i=1]$	$\mathbb{E}[Y_{i1}(1) G_i=1]$

$$\tau_{ATT} = \mathbb{E}[Y_{i1}(1)|G_i = 1] - \mathbb{E}[Y_{i1}(0)|G_i = 1]$$

	Time period		
	Pre-period $(t = 0)$	Post-period $(t = 1)$	
Control group $(G_i = 0)$	$\mathbb{E}[Y_{i0}(0) G_i=0]$	$\mathbb{E}[Y_{i1}(0) G_i=0]$	
Treated group $(G_i = 1)$	$\mathbb{E}[Y_{i0}(0) G_i=1]$	$\mathbb{E}[Y_{i1}(1) G_i=1]$	

- Cross-sectional design
 - · Assumption: mean independence of treatment

$$\mathbb{E}[Y_{i1}(0)|G_i = 1] = \mathbb{E}[Y_{i1}(0)|G_i = 0]$$

• Use post-treatment control group:

$$\tau_{ATT} = \mathbb{E}[Y_{i1}|G_i = 1] - \mathbb{E}[Y_{i1}|G_i = 0]$$

$$\tau_{ATT} = \mathbb{E}[Y_{i1}(1)|G_i = 1] - \mathbb{E}[Y_{i1}(0)|G_i = 1]$$

	Time period	
	Pre-period $(t = 0)$	Post-period $(t = 1)$
Control group $(G_i = 0)$	$\mathbb{E}[Y_{i0}(0) G_i=0]$	$\mathbb{E}[Y_{i1}(0) G_i=0]$
Treated group $(G_i = 1)$	$\mathbb{E}[Y_{i0}(0) G_i=1]$	$\mathbb{E}[Y_{i1}(1) G_i=1]$

- Before-and-after design
 - Assumption: no trends

$$\mathbb{E}[Y_{i1}(0)|G_i = 1] = \mathbb{E}[Y_{i0}(0)|G_i = 1]$$

• Use pre-period outcome in treated group:

$$\tau_{ATT} = \mathbb{E}[Y_{i1}|G_i = 1] - \mathbb{E}[Y_{i0}|G_i = 1]$$

$$\tau_{ATT} = \mathbb{E}[Y_{i1}(1)|G_i = 1] - \mathbb{E}[Y_{i1}(0)|G_i = 1]$$

	Time period	
	Pre-period $(t = 0)$	Post-period $(t = 1)$
Control group $(G_i = 0)$	$\mathbb{E}[Y_{i0}(0) G_i=0]$	$\mathbb{E}[Y_{i1}(0) G_i=0]$
Treated group $(G_i = 1)$	$\mathbb{E}[Y_{i0}(0) G_i=1]$	$\mathbb{E}[Y_{i1}(1) G_i=1]$

- Difference-in-differences:
 - Assumption: parallel trends

$$\mathbb{E}[Y_{i1}(0) - Y_{i0}(0)|G_i = 0] = \mathbb{E}[Y_{i1}(0) - Y_{i0}(0)|G_i = 1]$$

• Use pre-period treated outcome plus trend in control group:

$$\begin{aligned} \boldsymbol{\tau}_{ATT} = & (\mathbb{E}[Y_{i1}|G_i=1] - \mathbb{E}[Y_{i0}|G_i=1]) \\ & - (\mathbb{E}[Y_{i1}|G_i=0] - \mathbb{E}[Y_{i0}|G_i=0]) \end{aligned}$$

$$\mathbb{E}[Y_{i1}(0) - Y_{i0}(0) | G_i = 0] = \mathbb{E}[Y_{i1}(0) - Y_{i0}(0) | G_i = 1]$$

• Key assumption of differences-in-differences: parallel trends

$$\mathbb{E}[Y_{i1}(0) - Y_{i0}(0)|G_i = 0] = \mathbb{E}[Y_{i1}(0) - Y_{i0}(0)|G_i = 1]$$

- Key assumption of differences-in-differences: parallel trends
- Interpretation:

$$\mathbb{E}[Y_{i1}(0) - Y_{i0}(0)|G_i = 0] = \mathbb{E}[Y_{i1}(0) - Y_{i0}(0)|G_i = 1]$$

- Key assumption of differences-in-differences: **parallel trends**
- Interpretation:
 - Secular trend in the control group is a good proxy how the treated group would have changed over time without treatment.

$$\mathbb{E}[Y_{i1}(0) - Y_{i0}(0)|G_i = 0] = \mathbb{E}[Y_{i1}(0) - Y_{i0}(0)|G_i = 1]$$

- Key assumption of differences-in-differences: parallel trends
- Interpretation:
 - Secular trend in the control group is a good proxy how the treated group would have changed over time without treatment.
- Why is this weaker than other assumption?

$$\mathbb{E}[Y_{i1}(0) - Y_{i0}(0)|G_i = 0] = \mathbb{E}[Y_{i1}(0) - Y_{i0}(0)|G_i = 1]$$

- Key assumption of differences-in-differences: **parallel trends**
- Interpretation:
 - Secular trend in the control group is a good proxy how the treated group would have changed over time without treatment.
- Why is this weaker than other assumption?
 - Allows for time-constant unmeasured confounding between Y_{it} and G_i

$$\mathbb{E}[Y_{i1}(0) - Y_{i0}(0)|G_i = 0] = \mathbb{E}[Y_{i1}(0) - Y_{i0}(0)|G_i = 1]$$

- Key assumption of differences-in-differences: parallel trends
- Interpretation:
 - Secular trend in the control group is a good proxy how the treated group would have changed over time without treatment.
- Why is this weaker than other assumption?
 - Allows for time-constant unmeasured confounding between Y_{it} and G_i
 - Allows for (common) secular trends in the outcome over time (unlike FE).

$$\mathbb{E}[Y_{i1}(0) - Y_{i0}(0)|G_i = 0] = \mathbb{E}[Y_{i1}(0) - Y_{i0}(0)|G_i = 1]$$

- Key assumption of differences-in-differences: parallel trends
- Interpretation:
 - Secular trend in the control group is a good proxy how the treated group would have changed over time without treatment.
- Why is this weaker than other assumption?
 - Allows for time-constant unmeasured confounding between Y_{it} and G_i
 - Allows for (common) secular trends in the outcome over time (unlike FE).
- Not invariant to nonlinear transformations!

$$\mathbb{E}[Y_{i1}(0) - Y_{i0}(0)|G_i = 0] = \mathbb{E}[Y_{i1}(0) - Y_{i0}(0)|G_i = 1]$$

- Key assumption of differences-in-differences: parallel trends
- Interpretation:
 - Secular trend in the control group is a good proxy how the treated group would have changed over time without treatment.
- Why is this weaker than other assumption?
 - Allows for time-constant unmeasured confounding between Y_{it} and G_i
 - Allows for (common) secular trends in the outcome over time (unlike FE).
- Not invariant to nonlinear transformations!
 - Parallel trends for Y_{it} implies non-parallel trends for $log(Y_{it})$ and vice versa.

Parallel trends in a graph



Parallel trends in a graph



Identification

$$\begin{aligned} \tau_{ATT} &= (\mathbb{E}[Y_{i1}|G_i = 1] - \mathbb{E}[Y_{i0}|G_i = 1]) \\ &- (\mathbb{E}[Y_{i1}|G_i = 0] - \mathbb{E}[Y_{i0}|G_i = 0]) \end{aligned}$$

$$\begin{split} \tau_{ATT} &= (\mathbb{E}[Y_{i1}|G_i = 1] - \mathbb{E}[Y_{i0}|G_i = 1]) \\ &- (\mathbb{E}[Y_{i1}|G_i = 0] - \mathbb{E}[Y_{i0}|G_i = 0]) \end{split}$$

• Threat to identification: non-parallel trends

$$\begin{split} \tau_{ATT} &= (\mathbb{E}[Y_{i1}|G_i = 1] - \mathbb{E}[Y_{i0}|G_i = 1]) \\ &- (\mathbb{E}[Y_{i1}|G_i = 0] - \mathbb{E}[Y_{i0}|G_i = 0]) \end{split}$$

- Threat to identification: non-parallel trends
 - unmeasured time-varying confounding

$$\begin{aligned} \tau_{ATT} &= (\mathbb{E}[Y_{i1}|G_i = 1] - \mathbb{E}[Y_{i0}|G_i = 1]) \\ &- (\mathbb{E}[Y_{i1}|G_i = 0] - \mathbb{E}[Y_{i0}|G_i = 0]) \end{aligned}$$

- Threat to identification: non-parallel trends
 - unmeasured time-varying confounding
 - Ashenfelter's dip: empirical finding that people who enroll in job training programs see their earnings decline prior to that training.

$$\begin{aligned} \tau_{ATT} &= (\mathbb{E}[Y_{i1}|G_i = 1] - \mathbb{E}[Y_{i0}|G_i = 1]) \\ &- (\mathbb{E}[Y_{i1}|G_i = 0] - \mathbb{E}[Y_{i0}|G_i = 0]) \end{aligned}$$

- Threat to identification: non-parallel trends
 - unmeasured time-varying confounding
 - Ashenfelter's dip: empirical finding that people who enroll in job training programs see their earnings decline prior to that training.
- Falsification test: check pre-treatment parallel trends.

$$\begin{aligned} \tau_{ATT} &= (\mathbb{E}[Y_{i1}|G_i = 1] - \mathbb{E}[Y_{i0}|G_i = 1]) \\ &- (\mathbb{E}[Y_{i1}|G_i = 0] - \mathbb{E}[Y_{i0}|G_i = 0]) \end{aligned}$$

- Threat to identification: non-parallel trends
 - unmeasured time-varying confounding
 - Ashenfelter's dip: empirical finding that people who enroll in job training programs see their earnings decline prior to that training.
- Falsification test: check pre-treatment parallel trends.
 - Doesn't imply parallel trends hold for the post-period however!

Checking parallel trends (de Kadt/Larreguy, 2018)



• Estimation with panel data:

$$\widehat{\tau}_{\mathsf{ATT}} = \underbrace{\frac{1}{n_1} \sum_{i=1}^n G_i \{Y_{i1} - Y_{i0}\}}_{i=1} - \underbrace{\frac{1}{n_0} \sum_{i=1}^n (1 - G_i) \{Y_{i1} - Y_{i0}\}}_{i=1}$$

average trend in treated group

average trend in the control group

• Estimation with panel data:

$$\widehat{\tau}_{\mathsf{ATT}} = \underbrace{\frac{1}{n_1} \sum_{i=1}^n G_i \left\{ Y_{i1} - Y_{i0} \right\}}_{\text{average trend in treated group}} - \underbrace{\frac{1}{n_0} \sum_{i=1}^n (1 - G_i) \left\{ Y_{i1} - Y_{i0} \right\}}_{\text{average trend in the control group}}$$

• Standard errors from standard difference in means.

$$\widehat{\tau}_{\mathsf{ATT}} = \underbrace{\frac{1}{n_1}\sum_{i=1}^n G_i\left\{Y_{i1} - Y_{i0}\right\}}_{\text{average trend in treated group}} - \underbrace{\frac{1}{n_0}\sum_{i=1}^n (1 - G_i)\left\{Y_{i1} - Y_{i0}\right\}}_{\text{average trend in the control group}}$$

- · Standard errors from standard difference in means.
- Regression implementation:

$$\widehat{\tau}_{\mathsf{ATT}} = \underbrace{\frac{1}{n_1} \sum_{i=1}^n G_i \left\{ Y_{i1} - Y_{i0} \right\}}_{\text{average trend in treated group}} - \underbrace{\frac{1}{n_0} \sum_{i=1}^n (1 - G_i) \left\{ Y_{i1} - Y_{i0} \right\}}_{\text{average trend in the control group}}$$

- · Standard errors from standard difference in means.
- Regression implementation:
 - Regress $\Delta Y_i = Y_{i1} Y_{i0}$ on G_i .

$$\widehat{\tau}_{\mathsf{ATT}} = \underbrace{\frac{1}{n_1}\sum_{i=1}^n G_i\left\{Y_{i1} - Y_{i0}\right\}}_{\text{average trend in treated group}} - \underbrace{\frac{1}{n_0}\sum_{i=1}^n (1 - G_i)\left\{Y_{i1} - Y_{i0}\right\}}_{\text{average trend in the control group}}$$

- · Standard errors from standard difference in means.
- Regression implementation:
 - Regress $\Delta Y_i = Y_{i1} Y_{i0}$ on G_i .
 - Use (cluster) robust SEs

$$\widehat{\tau}_{\mathsf{ATT}} = \underbrace{\frac{1}{n_1}\sum_{i=1}^n G_i\left\{Y_{i1} - Y_{i0}\right\}}_{\text{average trend in treated group}} - \underbrace{\frac{1}{n_0}\sum_{i=1}^n (1 - G_i)\left\{Y_{i1} - Y_{i0}\right\}}_{\text{average trend in the control group}}$$

- · Standard errors from standard difference in means.
- Regression implementation:
 - Regress $\Delta Y_i = Y_{i1} Y_{i0}$ on G_i .
 - Use (cluster) robust SEs
- Also possible to use DID on repeated cross sections.

DID and linear two-way fixed effects

• Linear two-way (group and time) fixed effect model:

$$Y_{it} = \alpha + \gamma G_i + \beta t + \tau D_{it} + \varepsilon_{it}$$
• Linear two-way (group and time) fixed effect model:

$$Y_{it} = \alpha + \gamma G_i + \beta t + \tau D_{it} + \varepsilon_{it}$$

• Fixed effect for group and time.

$$Y_{it} = \alpha + \gamma G_i + \beta t + \tau D_{it} + \varepsilon_{it}$$

- Fixed effect for group and time.
- Be sure to cluster by unit (or level of treatment assignment)

$$Y_{it} = \alpha + \gamma G_i + \beta t + \tau D_{it} + \varepsilon_{it}$$

- Fixed effect for group and time.
- Be sure to cluster by unit (or level of treatment assignment)
- Coefficient on D_{it} equivalent to DID estimation.

$$Y_{it} = \alpha + \gamma G_i + \beta t + \tau D_{it} + \varepsilon_{it}$$

- Fixed effect for group and time.
- Be sure to cluster by unit (or level of treatment assignment)
- Coefficient on D_{it} equivalent to DID estimation.
- Only holds for the 2 group, 2 period case!

$$Y_{it} = \alpha + \gamma G_i + \beta t + \tau D_{it} + \varepsilon_{it}$$

- Fixed effect for group and time.
- Be sure to cluster by unit (or level of treatment assignment)
- Coefficient on D_{it} equivalent to DID estimation.
- Only holds for the 2 group, 2 period case!
 - Large new literature on interpretation of TWFE in more general cases.

$$Y_{it} = \alpha + \gamma G_i + \beta t + \tau D_{it} + \varepsilon_{it}$$

- Fixed effect for group and time.
- Be sure to cluster by unit (or level of treatment assignment)
- Coefficient on D_{it} equivalent to DID estimation.
- Only holds for the 2 group, 2 period case!
 - Large new literature on interpretation of TWFE in more general cases.
 - Basically, TWFE is an odd weighted average of DID effects with sometimes negative weights.

• Alternative identification assumption:

• Alternative identification assumption:

 $Y_{i1}(0) \perp\!\!\!\perp G_i \mid Y_{i0}$

• Doesn't imply and isn't implied by parallel trends.

• Alternative identification assumption:

- Doesn't imply and isn't implied by parallel trends.
- Benefit over parallel trends: it is scale-free.

• Alternative identification assumption:

- Doesn't imply and isn't implied by parallel trends.
- Benefit over parallel trends: it is scale-free.
- Equivalent to parallel trends if $\mathbb{E}[Y_{i0} \mid G_i = 1] = \mathbb{E}[Y_{i0} \mid G_i = 0]$

• Alternative identification assumption:

- Doesn't imply and isn't implied by parallel trends.
- Benefit over parallel trends: it is scale-free.
- Equivalent to parallel trends if $\mathbb{E}[Y_{i0} \mid G_i = 1] = \mathbb{E}[Y_{i0} \mid G_i = 0]$
- Different ideas about why there is imbalance on the LDV:

• Alternative identification assumption:

- Doesn't imply and isn't implied by parallel trends.
- Benefit over parallel trends: it is scale-free.
- Equivalent to parallel trends if $\mathbb{E}[Y_{i0} \mid G_i = 1] = \mathbb{E}[Y_{i0} \mid G_i = 0]$
- Different ideas about why there is imbalance on the LDV:
 - DID: time-constant unmeasured confounder creates imbalance.

• Alternative identification assumption:

- Doesn't imply and isn't implied by parallel trends.
- Benefit over parallel trends: it is scale-free.
- Equivalent to parallel trends if $\mathbb{E}[Y_{i0} \mid G_i = 1] = \mathbb{E}[Y_{i0} \mid G_i = 0]$
- Different ideas about why there is imbalance on the LDV:
 - DID: time-constant unmeasured confounder creates imbalance.
 - LDV: previous outcome directly affects treatment assignment.

• Estimator: estimate CEF $\mathbb{E}[Y_{i1} | Y_{i0}, G_i] = \alpha + \rho Y_{i0} + \tau G_i$

$$\widehat{F}_{LDV} = \underbrace{\frac{1}{n_1} \sum_{i=1}^{n} G_i Y_{i1} - \frac{1}{n_0} \sum_{i=1}^{n} (1 - G_i) Y_{i1}}_{\text{difference in post period}} - \widehat{\rho}_{LDV} \underbrace{\left\{ \frac{1}{n_1} \sum_{i=1}^{n} G_i Y_{i0} - \frac{1}{n_0} \sum_{i=1}^{n} (1 - G_i) Y_{i0} \right\}}_{\text{difference in post period}}$$

difference in pre period

• Estimator: estimate CEF $\mathbb{E}[Y_{i1} | Y_{i0}, G_i] = \alpha + \rho Y_{i0} + \tau G_i$

$$\begin{split} \widehat{\tau}_{LDV} &= \underbrace{\frac{1}{n_1} \sum_{i=1}^n G_i Y_{i1} - \frac{1}{n_0} \sum_{i=1}^n (1 - G_i) Y_{i1}}_{\text{difference in post period}} \\ &- \widehat{\rho}_{LDV} \underbrace{\left\{ \frac{1}{n_1} \sum_{i=1}^n G_i Y_{i0} - \frac{1}{n_0} \sum_{i=1}^n (1 - G_i) Y_{i0} \right\}}_{\text{difference in pre period}} \end{split}$$

• If
$$\hat{\rho}_{LDV} = 1$$
 then $\hat{\tau}_{DID} = \hat{\tau}_{LDV}$ and if $0 \le \hat{\rho}_{LDV} < 1$:

• Estimator: estimate CEF $\mathbb{E}[Y_{i1} | Y_{i0}, G_i] = \alpha + \rho Y_{i0} + \tau G_i$

$$\widehat{\tau}_{LDV} = \underbrace{\frac{1}{n_1} \sum_{i=1}^n G_i Y_{i1} - \frac{1}{n_0} \sum_{i=1}^n (1 - G_i) Y_{i1}}_{\text{difference in post period}} - \widehat{\rho}_{LDV} \underbrace{\left\{ \frac{1}{n_1} \sum_{i=1}^n G_i Y_{i0} - \frac{1}{n_0} \sum_{i=1}^n (1 - G_i) Y_{i0} \right\}}_{\text{difference in preperiod}}$$

• If
$$\hat{\rho}_{LDV} = 1$$
 then $\hat{\tau}_{DID} = \hat{\tau}_{LDV}$ and if $0 \le \hat{\rho}_{LDV} < 1$:

• If $G_i = 1$ has higher baseline outcomes $\rightsquigarrow \widehat{\tau}_{LDV} > \widehat{\tau}_{DID}$.

• Estimator: estimate CEF $\mathbb{E}[Y_{i1} | Y_{i0}, G_i] = \alpha + \rho Y_{i0} + \tau G_i$

$$\widehat{\tau}_{LDV} = \underbrace{\frac{1}{n_1} \sum_{i=1}^n G_i Y_{i1} - \frac{1}{n_0} \sum_{i=1}^n (1 - G_i) Y_{i1}}_{\text{difference in post period}} - \widehat{\rho}_{LDV} \underbrace{\left\{ \frac{1}{n_1} \sum_{i=1}^n G_i Y_{i0} - \frac{1}{n_0} \sum_{i=1}^n (1 - G_i) Y_{i0} \right\}}_{\text{difference in pre-period}}$$

- If
$$\hat{\rho}_{LDV} = 1$$
 then $\widehat{\tau}_{DID} = \widehat{\tau}_{LDV}$ and if $0 \leq \hat{\rho}_{LDV} < 1$:

- If $G_i = 1$ has higher baseline outcomes $\rightsquigarrow \hat{\tau}_{LDV} > \hat{\tau}_{DID}$.
- If $G_i = 1$ has lower baseline outcomes $\rightsquigarrow \widehat{\tau}_{DID} > \widehat{\tau}_{LDV}$.

• Estimator: estimate CEF $\mathbb{E}[Y_{i1} | Y_{i0}, G_i] = \alpha + \rho Y_{i0} + \tau G_i$

$$\widehat{r}_{LDV} = \underbrace{\frac{1}{n_1} \sum_{i=1}^n G_i Y_{i1} - \frac{1}{n_0} \sum_{i=1}^n (1 - G_i) Y_{i1}}_{\text{difference in post period}} - \widehat{\rho}_{LDV} \underbrace{\left\{ \frac{1}{n_1} \sum_{i=1}^n G_i Y_{i0} - \frac{1}{n_0} \sum_{i=1}^n (1 - G_i) Y_{i0} \right\}}_{\text{difference in preperiod}}$$

- If $\hat{\rho}_{LDV} = 1$ then $\hat{\tau}_{DID} = \hat{\tau}_{LDV}$ and if $0 \le \hat{\rho}_{LDV} < 1$:
 - If $G_i = 1$ has higher baseline outcomes $\rightsquigarrow \widehat{\tau}_{LDV} > \widehat{\tau}_{DID}$.
 - If $G_i = 1$ has lower baseline outcomes $\rightsquigarrow \widehat{\tau}_{DID} > \widehat{\tau}_{LDV}$.
- Bracketing relationship: if you willing to assume parallel trends or LDV,

 $\mathbb{E}[\widehat{\tau}_{\textit{LDV}}] \geq \tau_{\textit{att}} \geq \mathbb{E}[\widehat{\tau}_{\textit{DID}}]$

• Estimator: estimate CEF $\mathbb{E}[Y_{i1} | Y_{i0}, G_i] = \alpha + \rho Y_{i0} + \tau G_i$

$$\widehat{T}_{LDV} = \underbrace{\frac{1}{n_1} \sum_{i=1}^n G_i Y_{i1} - \frac{1}{n_0} \sum_{i=1}^n (1 - G_i) Y_{i1}}_{\text{difference in post period}} - \widehat{\rho}_{LDV} \underbrace{\left\{ \frac{1}{n_1} \sum_{i=1}^n G_i Y_{i0} - \frac{1}{n_0} \sum_{i=1}^n (1 - G_i) Y_{i0} \right\}}_{\text{difference in preperiod}}$$

• If
$$\hat{\rho}_{LDV} = 1$$
 then $\hat{\tau}_{DID} = \hat{\tau}_{LDV}$ and if $0 \le \hat{\rho}_{LDV} < 1$:

- If $G_i = 1$ has higher baseline outcomes $\rightsquigarrow \hat{\tau}_{LDV} > \hat{\tau}_{DID}$.
- If $G_i = 1$ has lower baseline outcomes $\rightsquigarrow \widehat{\tau}_{DID} > \widehat{\tau}_{LDV}$.
- Bracketing relationship: if you willing to assume parallel trends or LDV,

$$\mathbb{E}[\widehat{\tau}_{LDV}] \geq \tau_{\mathrm{att}} \geq \mathbb{E}[\widehat{\tau}_{DID}]$$

• Holds nonparametrically as well.

• Up until now, we assumed unconditional parallel trends. What if this doesn't hold?

- Up until now, we assumed unconditional parallel trends. What if this doesn't hold?
- · Alternative identification: conditional parallel trends

 $E[Y_{i1}(0) - Y_{i0}(0) \mid \mathbf{X}_i, G_i = 1] = E[Y_{i1}(0) - Y_{i0}(0) \mid \mathbf{X}_i, G_i = 0]$

- Up until now, we assumed unconditional parallel trends. What if this doesn't hold?
- Alternative identification: conditional parallel trends

$$E[Y_{i1}(0) - Y_{i0}(0) \mid \mathbf{X}_i, G_i = 1] = E[Y_{i1}(0) - Y_{i0}(0) \mid \mathbf{X}_i, G_i = 0]$$

• What does this assumption say? It says that the potential trend under control is the same for the control and treated groups, conditional on covariates.

- Up until now, we assumed unconditional parallel trends. What if this doesn't hold?
- · Alternative identification: conditional parallel trends

$$E[Y_{i1}(0) - Y_{i0}(0) \mid \mathbf{X}_i, G_i = 1] = E[Y_{i1}(0) - Y_{i0}(0) \mid \mathbf{X}_i, G_i = 0]$$

- What does this assumption say? It says that the potential trend under control is the same for the control and treated groups, conditional on covariates.
 - Units that are similar at baseline will follow similar paths under no treatment.

- Up until now, we assumed unconditional parallel trends. What if this doesn't hold?
- Alternative identification: conditional parallel trends

$$E[Y_{i1}(0) - Y_{i0}(0) \mid \mathbf{X}_i, G_i = 1] = E[Y_{i1}(0) - Y_{i0}(0) \mid \mathbf{X}_i, G_i = 0]$$

- What does this assumption say? It says that the potential trend under control is the same for the control and treated groups, conditional on covariates.
 - Units that are similar at baseline will follow similar paths under no treatment.
- Matching: conduct DID analysis on units with similar values of X,

• How to estimate regression DID without strong linearity assumptions?

- How to estimate regression DID without strong linearity assumptions?
- Abadie (2005) derives weighting estimators in this setting:

$$\mathbb{E}[Y_{i1}(1) - Y_{i1}(0) \mid G_i = 1] = \mathbb{E}\left[\frac{(Y_{i1} - Y_{i0})}{\mathbb{P}(G_i = 1)} \cdot \frac{G_i - \mathbb{P}(G_i = 1 \mid \mathbf{X}_i)}{1 - \mathbb{P}(G_i = 1 \mid \mathbf{X}_i)}\right]$$

- How to estimate regression DID without strong linearity assumptions?
- Abadie (2005) derives weighting estimators in this setting:

$$\mathbb{E}[Y_{i1}(1) - Y_{i1}(0) \mid G_i = 1] = \mathbb{E}\left[\frac{(Y_{i1} - Y_{i0})}{\mathbb{P}(G_i = 1)} \cdot \frac{G_i - \mathbb{P}(G_i = 1 \mid \mathbf{X}_i)}{1 - \mathbb{P}(G_i = 1 \mid \mathbf{X}_i)}\right]$$

 Reweights control group to have the same distribution of X_i as treated group.

- How to estimate regression DID without strong linearity assumptions?
- Abadie (2005) derives weighting estimators in this setting:

$$\mathbb{E}[Y_{i1}(1) - Y_{i1}(0) \mid G_i = 1] = \mathbb{E}\left[\frac{(Y_{i1} - Y_{i0})}{\mathbb{P}(G_i = 1)} \cdot \frac{G_i - \mathbb{P}(G_i = 1 \mid \mathbf{X}_i)}{1 - \mathbb{P}(G_i = 1 \mid \mathbf{X}_i)}\right]$$

- Reweights control group to have the same distribution of X_i as treated group.
- Have to estimate the **propensity score** $\mathbb{P}(G_i = 1 | \mathbf{X}_i)$

- How to estimate regression DID without strong linearity assumptions?
- Abadie (2005) derives weighting estimators in this setting:

$$\mathbb{E}[Y_{i1}(1) - Y_{i1}(0) \mid G_i = 1] = \mathbb{E}\left[\frac{(Y_{i1} - Y_{i0})}{\mathbb{P}(G_i = 1)} \cdot \frac{G_i - \mathbb{P}(G_i = 1 \mid \mathbf{X}_i)}{1 - \mathbb{P}(G_i = 1 \mid \mathbf{X}_i)}\right]$$

- Reweights control group to have the same distribution of X_i as treated group.
- Have to estimate the **propensity score** $\mathbb{P}(G_i = 1 | \mathbf{X}_i)$
 - Possible model misspecification!

2/ Fixed effects

• "One way" fixed effects generalizes the before/after design.

- "One way" fixed effects generalizes the before/after design.
 - Arbitrary treatment timing, covariates, etc.

- "One way" fixed effects generalizes the before/after design.
 - Arbitrary treatment timing, covariates, etc.
 - Units: *i* = 1, ..., *n*

- "One way" fixed effects generalizes the before/after design.
 - Arbitrary treatment timing, covariates, etc.
 - Units: *i* = 1, ..., *n*
 - Causal ordering with time: covariates X_{it}, treatment D_{it}, outcome Y_{it}

- "One way" fixed effects generalizes the before/after design.
 - Arbitrary treatment timing, covariates, etc.
 - Units: *i* = 1, ..., *n*
 - Causal ordering with time: covariates X_{it}, treatment D_{it}, outcome Y_{it}
 - History of a variable: $\overline{D}_{it} = (D_{i1}, \dots, D_{it})$ and $\overline{D}_i \equiv \overline{D}_{iT}$

- "One way" fixed effects generalizes the before/after design.
 - Arbitrary treatment timing, covariates, etc.
 - Units: *i* = 1, ..., *n*
 - Causal ordering with time: covariates X_{it}, treatment D_{it}, outcome Y_{it}
 - History of a variable: $\overline{D}_{it} = (D_{i1}, \dots, D_{it})$ and $\overline{D}_i \equiv \overline{D}_{iT}$
- Linear fixed effects model: $Y_{it} = \alpha_i + \tau D_{it} + \mathbf{X}'_i \boldsymbol{\beta} + \varepsilon_{it}$
- "One way" fixed effects generalizes the before/after design.
 - Arbitrary treatment timing, covariates, etc.
 - Units: *i* = 1, ..., *n*
 - Causal ordering with time: covariates X_{it}, treatment D_{it}, outcome Y_{it}
 - History of a variable: $\overline{D}_{it} = (D_{i1}, \dots, D_{it})$ and $\overline{D}_i \equiv \overline{D}_{iT}$
- Linear fixed effects model: $Y_{it} = \alpha_i + \tau D_{it} + \mathbf{X}'_i \boldsymbol{\beta} + \varepsilon_{it}$
 - Key assumption: **strict exogeneity** $\mathbb{E}[\varepsilon_{it} \mid \overline{\mathbf{X}}_i, \overline{D}_i, \alpha_i] = 0$

- "One way" fixed effects generalizes the before/after design.
 - Arbitrary treatment timing, covariates, etc.
 - Units: *i* = 1, ..., *n*
 - Causal ordering with time: covariates X_{it}, treatment D_{it}, outcome Y_{it}
 - History of a variable: $\overline{D}_{it} = (D_{i1}, \dots, D_{it})$ and $\overline{D}_i \equiv \overline{D}_{iT}$
- Linear fixed effects model: $Y_{it} = \alpha_i + \tau D_{it} + \mathbf{X}'_i \boldsymbol{\beta} + \varepsilon_{it}$
 - Key assumption: **strict exogeneity** $\mathbb{E}[\varepsilon_{it} \mid \overline{\mathbf{X}}_i, \overline{D}_i, \alpha_i] = 0$
 - Implies **no feedback** between outcome and treatment $(Y_{it} \rightarrow D_{i,t+1})$

- "One way" fixed effects generalizes the before/after design.
 - Arbitrary treatment timing, covariates, etc.
 - Units: *i* = 1, ..., *n*
 - Causal ordering with time: covariates X_{it}, treatment D_{it}, outcome Y_{it}
 - History of a variable: $\overline{D}_{it} = (D_{i1}, \dots, D_{it})$ and $\overline{D}_i \equiv \overline{D}_{iT}$
- Linear fixed effects model: $Y_{it} = \alpha_i + \tau D_{it} + \mathbf{X}'_i \boldsymbol{\beta} + \varepsilon_{it}$
 - Key assumption: **strict exogeneity** $\mathbb{E}[\varepsilon_{it} \mid \overline{\mathbf{X}}_i, \overline{D}_i, \alpha_i] = 0$
 - Implies **no feedback** between outcome and treatment $(Y_{it} \rightarrow D_{i,t+1})$
 - * \rightsquigarrow LDV cannot be a confounder!

- "One way" fixed effects generalizes the before/after design.
 - Arbitrary treatment timing, covariates, etc.
 - Units: *i* = 1, ..., *n*
 - Causal ordering with time: covariates X_{it}, treatment D_{it}, outcome Y_{it}
 - History of a variable: $\overline{D}_{it} = (D_{i1}, \dots, D_{it})$ and $\overline{D}_i \equiv \overline{D}_{iT}$
- Linear fixed effects model: $Y_{it} = \alpha_i + \tau D_{it} + \mathbf{X}'_i \boldsymbol{\beta} + \varepsilon_{it}$
 - Key assumption: **strict exogeneity** $\mathbb{E}[\varepsilon_{it} \mid \overline{\mathbf{X}}_i, \overline{D}_i, \alpha_i] = 0$
 - Implies **no feedback** between outcome and treatment $(Y_{it} \rightarrow D_{i,t+1})$
 - → LDV cannot be a confounder!
 - Imai and Kim (2019, AJPS) give clarification on these identification issues.

- "One way" fixed effects generalizes the before/after design.
 - Arbitrary treatment timing, covariates, etc.
 - Units: *i* = 1, ..., *n*
 - Causal ordering with time: covariates X_{it}, treatment D_{it}, outcome Y_{it}
 - History of a variable: $\overline{D}_{it} = (D_{i1}, \dots, D_{it})$ and $\overline{D}_i \equiv \overline{D}_{iT}$
- Linear fixed effects model: $Y_{it} = \alpha_i + \tau D_{it} + \mathbf{X}'_i \boldsymbol{\beta} + \varepsilon_{it}$
 - Key assumption: **strict exogeneity** $\mathbb{E}[\varepsilon_{it} \mid \overline{\mathbf{X}}_i, \overline{D}_i, \alpha_i] = 0$
 - Implies **no feedback** between outcome and treatment $(Y_{it} \rightarrow D_{i,t+1})$
 - \rightsquigarrow LDV cannot be a confounder!
 - Imai and Kim (2019, AJPS) give clarification on these identification issues.
- Implicit assumption of **no carryover**? $Y_{it}(d_1, ..., d_t) = Y_{it}(d_t)$

- "One way" fixed effects generalizes the before/after design.
 - Arbitrary treatment timing, covariates, etc.
 - Units: *i* = 1, ..., *n*
 - Causal ordering with time: covariates X_{it}, treatment D_{it}, outcome Y_{it}
 - History of a variable: $\overline{D}_{it} = (D_{i1}, \dots, D_{it})$ and $\overline{D}_i \equiv \overline{D}_{iT}$
- Linear fixed effects model: $Y_{it} = \alpha_i + \tau D_{it} + \mathbf{X}'_i \boldsymbol{\beta} + \varepsilon_{it}$
 - Key assumption: **strict exogeneity** $\mathbb{E}[\varepsilon_{it} \mid \overline{\mathbf{X}}_i, \overline{D}_i, \alpha_i] = 0$
 - Implies **no feedback** between outcome and treatment $(Y_{it} \rightarrow D_{i,t+1})$
 - \rightsquigarrow LDV cannot be a confounder!
 - Imai and Kim (2019, AJPS) give clarification on these identification issues.
- Implicit assumption of **no carryover**? $Y_{it}(d_1, ..., d_t) = Y_{it}(d_t)$
 - More a choice of estimand: focuses on **contemporaneous** effect.

- "One way" fixed effects generalizes the before/after design.
 - Arbitrary treatment timing, covariates, etc.
 - Units: *i* = 1, ..., *n*
 - Causal ordering with time: covariates X_{it}, treatment D_{it}, outcome Y_{it}
 - History of a variable: $\overline{D}_{it} = (D_{i1}, \dots, D_{it})$ and $\overline{D}_i \equiv \overline{D}_{iT}$
- Linear fixed effects model: $Y_{it} = \alpha_i + \tau D_{it} + \mathbf{X}'_i \boldsymbol{\beta} + \varepsilon_{it}$
 - Key assumption: **strict exogeneity** $\mathbb{E}[\varepsilon_{it} \mid \overline{\mathbf{X}}_i, \overline{D}_i, \alpha_i] = 0$
 - Implies **no feedback** between outcome and treatment $(Y_{it} \rightarrow D_{i,t+1})$
 - \rightsquigarrow LDV cannot be a confounder!
 - Imai and Kim (2019, AJPS) give clarification on these identification issues.
- Implicit assumption of **no carryover**? $Y_{it}(d_1, ..., d_t) = Y_{it}(d_t)$
 - More a choice of estimand: focuses on **contemporaneous** effect.
 - Treatment history follows observed path through t 1: $Y_{it}(d_t) = Y_{it}(D_{i1}, \dots, D_{i,t-1}, d_t)$

- "One way" fixed effects generalizes the before/after design.
 - Arbitrary treatment timing, covariates, etc.
 - Units: *i* = 1, ..., *n*
 - Causal ordering with time: covariates X_{it}, treatment D_{it}, outcome Y_{it}
 - History of a variable: $\overline{D}_{it} = (D_{i1}, \dots, D_{it})$ and $\overline{D}_i \equiv \overline{D}_{iT}$
- Linear fixed effects model: $Y_{it} = \alpha_i + \tau D_{it} + \mathbf{X}'_i \boldsymbol{\beta} + \varepsilon_{it}$
 - Key assumption: **strict exogeneity** $\mathbb{E}[\varepsilon_{it} \mid \overline{\mathbf{X}}_i, \overline{D}_i, \alpha_i] = 0$
 - Implies **no feedback** between outcome and treatment $(Y_{it} \rightarrow D_{i,t+1})$
 - \rightsquigarrow LDV cannot be a confounder!
 - Imai and Kim (2019, AJPS) give clarification on these identification issues.
- Implicit assumption of **no carryover**? $Y_{it}(d_1, ..., d_t) = Y_{it}(d_t)$
 - More a choice of estimand: focuses on **contemporaneous** effect.
 - Treatment history follows observed path through t-1: $Y_{it}(d_t) = Y_{it}(D_{i1}, \dots, D_{i,t-1}, d_t)$
 - + \rightsquigarrow lags of treatments become part of time-varying confounders.

Strict exogeneity DAG



Strict exogeneity implied by strict ignorability $Y_{it}(d) \perp \overline{D}_i \mid \overline{X}_i, U_i$

• With linear models, two transformations can purge the fixed effects.

- With linear models, two transformations can purge the fixed effects.
- Within/FE transformation: $\ddot{Z}_{it} = Z_{it} T^{-1} \sum_{s=1}^{T} Z_{is}$

$$\ddot{Y}_{it} = \ddot{X}'_{it}\beta + \tau \ddot{D}_{it} + \ddot{\varepsilon}_{it}$$

- With linear models, two transformations can purge the fixed effects.
- Within/FE transformation: $\ddot{Z}_{it} = Z_{it} T^{-1} \sum_{s=1}^{T} Z_{is}$

$$\ddot{Y}_{it} = \ddot{X}'_{it}\beta + \tau \ddot{D}_{it} + \ddot{\varepsilon}_{it}$$

• Time-demeaning Y_{it} purges the time constant fixed effect.

- With linear models, two transformations can purge the fixed effects.
- Within/FE transformation: $\ddot{Z}_{it} = Z_{it} T^{-1} \sum_{s=1}^{T} Z_{is}$

$$\ddot{Y}_{it} = \ddot{X}'_{it}\beta + \tau \ddot{D}_{it} + \ddot{\varepsilon}_{it}$$

- Time-demeaning Y_{it} purges the time constant fixed effect.
- But they retain the same coefficients as the original model.

- With linear models, two transformations can purge the fixed effects.
- Within/FE transformation: $\ddot{Z}_{it} = Z_{it} T^{-1} \sum_{s=1}^{T} Z_{is}$

$$\ddot{Y}_{it} = \ddot{X}'_{it}\beta + \tau \ddot{D}_{it} + \ddot{\varepsilon}_{it}$$

- Time-demeaning Y_{it} purges the time constant fixed effect.
- But they retain the same coefficients as the original model.
- First differences: $\Delta Z_{it} = Z_{it} Z_{i,t-1}$

$$\Delta Y_{it} = \Delta \mathbf{X}'_{it} \boldsymbol{\beta} + \tau \Delta D_{it} + \Delta \varepsilon_{it}$$

- With linear models, two transformations can purge the fixed effects.
- Within/FE transformation: $\ddot{Z}_{it} = Z_{it} T^{-1} \sum_{s=1}^{T} Z_{is}$

$$\ddot{Y}_{it} = \ddot{X}'_{it}\beta + \tau \ddot{D}_{it} + \ddot{\varepsilon}_{it}$$

- Time-demeaning Y_{it} purges the time constant fixed effect.
- But they retain the same coefficients as the original model.
- First differences: $\Delta Z_{it} = Z_{it} Z_{i,t-1}$

$$\Delta Y_{it} = \Delta \mathbf{X}'_{it} \boldsymbol{\beta} + \tau \Delta D_{it} + \Delta \varepsilon_{it}$$

• Estimation: pooled OLS of either specification, $\hat{\tau}_{\rm fe}, \hat{\tau}_{\rm fd}$

- With linear models, two transformations can purge the fixed effects.
- Within/FE transformation: $\ddot{Z}_{it} = Z_{it} T^{-1} \sum_{s=1}^{T} Z_{is}$

$$\ddot{Y}_{it} = \ddot{X}'_{it}\beta + \tau \ddot{D}_{it} + \ddot{\varepsilon}_{it}$$

- Time-demeaning Y_{it} purges the time constant fixed effect.
- But they retain the same coefficients as the original model.
- First differences: $\Delta Z_{it} = Z_{it} Z_{i,t-1}$

$$\Delta Y_{it} = \Delta \mathbf{X}'_{it} \boldsymbol{\beta} + \tau \Delta D_{it} + \Delta \varepsilon_{it}$$

- Estimation: pooled OLS of either specification, $\widehat{\tau}_{\rm fe}, \widehat{\tau}_{\rm fd}$
 - Both consistent under strict exogeneity.

- With linear models, two transformations can purge the fixed effects.
- Within/FE transformation: $\ddot{Z}_{it} = Z_{it} T^{-1} \sum_{s=1}^{T} Z_{is}$

$$\ddot{Y}_{it} = \ddot{X}'_{it}\beta + \tau \ddot{D}_{it} + \ddot{\varepsilon}_{it}$$

- Time-demeaning Y_{it} purges the time constant fixed effect.
- But they retain the same coefficients as the original model.
- First differences: $\Delta Z_{it} = Z_{it} Z_{i,t-1}$

$$\Delta Y_{it} = \Delta \mathbf{X}'_{it} \boldsymbol{\beta} + \tau \Delta D_{it} + \Delta \varepsilon_{it}$$

- Estimation: pooled OLS of either specification, $\widehat{\tau}_{\rm fe}, \widehat{\tau}_{\rm fd}$
 - · Both consistent under strict exogeneity.
 - FE more efficient if original errors, ϵ_{it} , are serially uncorrelated.

- With linear models, two transformations can purge the fixed effects.
- Within/FE transformation: $\ddot{Z}_{it} = Z_{it} T^{-1} \sum_{s=1}^{T} Z_{is}$

$$\ddot{Y}_{it} = \ddot{X}'_{it}\beta + \tau \ddot{D}_{it} + \ddot{\varepsilon}_{it}$$

- Time-demeaning Y_{it} purges the time constant fixed effect.
- But they retain the same coefficients as the original model.
- First differences: $\Delta Z_{it} = Z_{it} Z_{i,t-1}$

$$\Delta Y_{it} = \Delta \mathbf{X}'_{it} \boldsymbol{\beta} + \tau \Delta D_{it} + \Delta \varepsilon_{it}$$

- Estimation: pooled OLS of either specification, $\widehat{\tau}_{\rm fe}, \widehat{\tau}_{\rm fd}$
 - Both consistent under strict exogeneity.
 - FE more efficient if original errors, ϵ_{it} , are serially uncorrelated.
 - FD more efficient if differences, $\Delta \varepsilon_{it}$, are serially uncorrelated.

- With linear models, two transformations can purge the fixed effects.
- Within/FE transformation: $\ddot{Z}_{it} = Z_{it} T^{-1} \sum_{s=1}^{T} Z_{is}$

$$\ddot{Y}_{it} = \ddot{X}'_{it}\beta + \tau \ddot{D}_{it} + \ddot{\varepsilon}_{it}$$

- Time-demeaning Y_{it} purges the time constant fixed effect.
- But they retain the same coefficients as the original model.
- First differences: $\Delta Z_{it} = Z_{it} Z_{i,t-1}$

$$\Delta Y_{it} = \Delta \mathbf{X}'_{it} \boldsymbol{\beta} + \tau \Delta D_{it} + \Delta \varepsilon_{it}$$

- Estimation: pooled OLS of either specification, $\widehat{\tau}_{\rm fe}, \widehat{\tau}_{\rm fd}$
 - Both consistent under strict exogeneity.
 - FE more efficient if original errors, ϵ_{it} , are serially uncorrelated.
 - FD more efficient if differences, $\Delta \varepsilon_{it}$, are serially uncorrelated.
 - Latter allows for substantial serial dependence in the original errors.

$$\underset{\alpha,\beta,\tau,\gamma}{\arg\max}\sum_{i=1}^{n}\sum_{t=1}^{T}\left(Y_{it}-\alpha-\mathbf{X}_{it}^{\prime}\beta-\tau D_{it}-\sum_{k=2}^{n}\gamma_{k}\mathbb{1}(i=k)\right)^{2}$$

• Within estimator can be implemented by adding unit dummy variables.

$$\underset{\alpha,\beta,\tau,\gamma}{\arg\max} \sum_{i=1}^{n} \sum_{t=1}^{T} \left(Y_{it} - \alpha - \mathbf{X}'_{it}\beta - \tau D_{it} - \sum_{k=2}^{n} \gamma_k \mathbb{1}(i=k) \right)^2$$

• Least squares dummy variable estimator reasonable for moderate n

$$\underset{\alpha,\beta,\tau,\gamma}{\arg\max}\sum_{i=1}^{n}\sum_{t=1}^{T}\left(Y_{it}-\alpha-\mathbf{X}_{it}^{\prime}\beta-\tau D_{it}-\sum_{k=2}^{n}\gamma_{k}\mathbb{1}(i=k)\right)^{2}$$

- Least squares dummy variable estimator reasonable for moderate *n*
- Computationally inefficient for large *n* (number of dummies grows with *n*)

$$\underset{\alpha,\beta,\tau,\gamma}{\arg\max}\sum_{i=1}^{n}\sum_{t=1}^{T}\left(Y_{it}-\alpha-\mathbf{X}_{it}^{\prime}\beta-\tau D_{it}-\sum_{k=2}^{n}\gamma_{k}\mathbb{1}(i=k)\right)^{2}$$

- Least squares dummy variable estimator reasonable for moderate *n*
- Computationally inefficient for large *n* (number of dummies grows with *n*)
- Best practice: cluster variances at the unit level.

$$\underset{\alpha,\beta,\tau,\gamma}{\arg\max}\sum_{i=1}^{n}\sum_{t=1}^{T}\left(Y_{it}-\alpha-\mathbf{X}_{it}^{\prime}\beta-\tau D_{it}-\sum_{k=2}^{n}\gamma_{k}\mathbb{1}(i=k)\right)^{2}$$

- Least squares dummy variable estimator reasonable for moderate *n*
- Computationally inefficient for large *n* (number of dummies grows with *n*)
- Best practice: cluster variances at the unit level.
 - With CR variance estimators, LSDV "double counts" degrees of freedom

$$\underset{\alpha,\beta,\tau,\gamma}{\arg\max}\sum_{i=1}^{n}\sum_{t=1}^{T}\left(Y_{it}-\alpha-\mathbf{X}_{it}^{\prime}\beta-\tau D_{it}-\sum_{k=2}^{n}\gamma_{k}\mathbb{1}(i=k)\right)^{2}$$

- Least squares dummy variable estimator reasonable for moderate *n*
- Computationally inefficient for large *n* (number of dummies grows with *n*)
- Best practice: cluster variances at the unit level.
 - With CR variance estimators, LSDV "double counts" degrees of freedom
 - · Better to use within estimator in that case.

$$\underset{\alpha,\beta,\tau,\gamma}{\arg\max}\sum_{i=1}^{n}\sum_{t=1}^{T}\left(Y_{it}-\alpha-\mathbf{X}_{it}^{\prime}\beta-\tau D_{it}-\sum_{k=2}^{n}\gamma_{k}\mathbb{1}(i=k)\right)^{2}$$

- Least squares dummy variable estimator reasonable for moderate *n*
- Computationally inefficient for large *n* (number of dummies grows with *n*)
- Best practice: cluster variances at the unit level.
 - With CR variance estimators, LSDV "double counts" degrees of freedom
 - Better to use within estimator in that case.
- Best choice: use canned packages.

$$\underset{\alpha,\beta,\tau,\gamma}{\arg\max}\sum_{i=1}^{n}\sum_{t=1}^{T}\left(Y_{it}-\alpha-\mathbf{X}_{it}^{\prime}\beta-\tau D_{it}-\sum_{k=2}^{n}\gamma_{k}\mathbb{1}(i=k)\right)^{2}$$

- Least squares dummy variable estimator reasonable for moderate *n*
- Computationally inefficient for large *n* (number of dummies grows with *n*)
- Best practice: cluster variances at the unit level.
 - With CR variance estimators, LSDV "double counts" degrees of freedom
 - · Better to use within estimator in that case.
- Best choice: use canned packages.
 - {fixest} in R, -reghdfe- in Stata

• LFE models assume constant treatment effects. What happens if not?

- LFE models assume constant treatment effects. What happens if not?
 - OLS typically biased because nonconstant effects induce correlation between treatment and error.

- LFE models assume constant treatment effects. What happens if not?
 - OLS typically biased because nonconstant effects induce correlation between treatment and error.
- With no covariates and no only treated/control units:

$$\widehat{\tau}_{\mathsf{fe}} \xrightarrow{p} \frac{\mathbb{E}\left[\left(\frac{\sum_{t} D_{it} Y_{it}}{\sum_{t} D_{it}} - \frac{\sum_{t} (1 - D_{it}) Y_{it}}{\sum_{t} (1 - D_{it})}\right) S_{i}^{2}\right]}{\mathbb{E}[S_{i}^{2}]} \neq \tau$$

- LFE models assume constant treatment effects. What happens if not?
 - OLS typically biased because nonconstant effects induce correlation between treatment and error.
- With no covariates and no only treated/control units:

$$\widehat{\tau}_{\mathsf{fe}} \xrightarrow{p} \frac{\mathbb{E}\left[\left(\frac{\sum_{t} D_{it} Y_{it}}{\sum_{t} D_{it}} - \frac{\sum_{t} (1 - D_{it}) Y_{it}}{\sum_{t} (1 - D_{it})}\right) S_{i}^{2}\right]}{\mathbb{E}[S_{i}^{2}]} \neq \tau$$

• S_i^2 is the within-unit treatment variance.

- LFE models assume constant treatment effects. What happens if not?
 - OLS typically biased because nonconstant effects induce correlation between treatment and error.
- With no covariates and no only treated/control units:

$$\widehat{\tau}_{\mathsf{fe}} \xrightarrow{p} \frac{\mathbb{E}\left[\left(\frac{\sum_{t} D_{it} Y_{it}}{\sum_{t} D_{it}} - \frac{\sum_{t} (1 - D_{it}) Y_{it}}{\sum_{t} (1 - D_{it})}\right) S_{i}^{2}\right]}{\mathbb{E}[S_{i}^{2}]} \neq \tau$$

- S_i^2 is the within-unit treatment variance.
- Units with even treatment/control split upweighted.

- LFE models assume constant treatment effects. What happens if not?
 - OLS typically biased because nonconstant effects induce correlation between treatment and error.
- With no covariates and no only treated/control units:

$$\widehat{\tau}_{\mathsf{fe}} \xrightarrow{p} \frac{\mathbb{E}\left[\left(\frac{\sum_{t} D_{it} Y_{it}}{\sum_{t} D_{it}} - \frac{\sum_{t} (1 - D_{it}) Y_{it}}{\sum_{t} (1 - D_{it})}\right) S_{i}^{2}\right]}{\mathbb{E}[S_{i}^{2}]} \neq \tau$$

- S_i^2 is the within-unit treatment variance.
- Units with even treatment/control split upweighted.
- Imai, Kim & Wang (2019, AJPS): use a matching to target the ATE.

- LFE models assume constant treatment effects. What happens if not?
 - OLS typically biased because nonconstant effects induce correlation between treatment and error.
- With no covariates and no only treated/control units:

$$\widehat{\tau}_{\mathsf{fe}} \xrightarrow{\mathsf{p}} \frac{\mathbb{E}\left[\left(\frac{\sum_{t} D_{it} Y_{it}}{\sum_{t} D_{it}} - \frac{\sum_{t} (1 - D_{it}) Y_{it}}{\sum_{t} (1 - D_{it})}\right) S_{i}^{2}\right]}{\mathbb{E}[S_{i}^{2}]} \neq \tau$$

- S_i^2 is the within-unit treatment variance.
- Units with even treatment/control split upweighted.
- Imai, Kim & Wang (2019, AJPS): use a matching to target the ATE.
 - Match treated and control periods within units (also weakens linearity).

- LFE models assume constant treatment effects. What happens if not?
 - OLS typically biased because nonconstant effects induce correlation between treatment and error.
- With no covariates and no only treated/control units:

$$\widehat{\tau}_{\mathsf{fe}} \xrightarrow{\mathsf{p}} \frac{\mathbb{E}\left[\left(\frac{\sum_{t} D_{it} Y_{it}}{\sum_{t} D_{it}} - \frac{\sum_{t} (1 - D_{it}) Y_{it}}{\sum_{t} (1 - D_{it})}\right) S_{i}^{2}\right]}{\mathbb{E}[S_{i}^{2}]} \neq \tau$$

- S_i^2 is the within-unit treatment variance.
- Units with even treatment/control split upweighted.
- Imai, Kim & Wang (2019, AJPS): use a matching to target the ATE.
 - Match treated and control periods within units (also weakens linearity).
 - {PanelMatch} R package.

Strict vs. sequential exogeneity/ignorability

• Strict exogeneity/ignorability is **very strong**.
- Strict exogeneity/ignorability is **very strong**.
 - Remember: rules out all outcome-treatment feedback.

- Strict exogeneity/ignorability is very strong.
 - Remember: rules out all outcome-treatment feedback.
- Weaker assumption: Sequential ignorability:

- Strict exogeneity/ignorability is very strong.
 - Remember: rules out all outcome-treatment feedback.
- Weaker assumption: Sequential ignorability:

 $Y_{it}(d) \perp\!\!\!\perp D_{it} \mid \overline{\mathbf{X}}_{it}, \overline{D}_{i,t-1}, \alpha_i$

• Allow Y_{it} to be related to future D_{i,t+s}

- Strict exogeneity/ignorability is very strong.
 - Remember: rules out all outcome-treatment feedback.
- Weaker assumption: Sequential ignorability:

- Allow Y_{it} to be related to future D_{i,t+s}
- This implies **sequential exogeneity** of the errors: $\mathbb{E}[\varepsilon_{it} \mid \overline{\mathbf{X}}_{it}, \overline{D}_{it}, \alpha_i] = 0.$

- Strict exogeneity/ignorability is very strong.
 - Remember: rules out all outcome-treatment feedback.
- Weaker assumption: Sequential ignorability:

- Allow Y_{it} to be related to future D_{i,t+s}
- This implies **sequential exogeneity** of the errors: $\mathbb{E}[\varepsilon_{it} \mid \overline{\mathbf{X}}_{it}, \overline{D}_{it}, \alpha_i] = 0.$
- Estimation to these dynamic panel models:

- Strict exogeneity/ignorability is very strong.
 - Remember: rules out all outcome-treatment feedback.
- Weaker assumption: Sequential ignorability:

- Allow Y_{it} to be related to future D_{i,t+s}
- This implies **sequential exogeneity** of the errors: $\mathbb{E}[\varepsilon_{it} \mid \overline{\mathbf{X}}_{it}, \overline{D}_{it}, \alpha_i] = 0.$
- Estimation to these dynamic panel models:
 - instrumental variables (Arellano and Bond) using lagged difference and levels as instruments (only valid for linear models).

- Strict exogeneity/ignorability is very strong.
 - Remember: rules out all outcome-treatment feedback.
- Weaker assumption: Sequential ignorability:

- Allow Y_{it} to be related to future D_{i,t+s}
- This implies **sequential exogeneity** of the errors: $\mathbb{E}[\varepsilon_{it} \mid \overline{\mathbf{X}}_{it}, \overline{D}_{it}, \alpha_i] = 0.$
- Estimation to these dynamic panel models:
 - instrumental variables (Arellano and Bond) using lagged difference and levels as instruments (only valid for linear models).
 - bias correction: estimate the bias and subtract it off (valid for nonlinear models too).

Effect of lagged treatments

• Focused on the contemporaneous effect of D_{it} .

- Focused on the contemporaneous effect of D_{it} .
- What about treatment histories $Y_{it}(d_{t-1}, d_t)$?

- Focused on the contemporaneous effect of D_{it} .
- What about treatment histories $Y_{it}(d_{t-1}, d_t)$?
- Very difficult, if not impossible with fixed effects models.

- Focused on the contemporaneous effect of D_{it} .
- What about treatment histories $Y_{it}(d_{t-1}, d_t)$?
- Very difficult, if not impossible with fixed effects models.
 - Complicated by the effect of treatment on time-varying confounders.

- Focused on the contemporaneous effect of D_{it} .
- What about treatment histories $Y_{it}(d_{t-1}, d_t)$?
- Very difficult, if not impossible with fixed effects models.
 - Complicated by the effect of treatment on time-varying confounders.
 - Pathways involving $\mathbf{X}_{it}(d_{t-1})$ difficult to identify.

- Focused on the contemporaneous effect of D_{it} .
- What about treatment histories $Y_{it}(d_{t-1}, d_t)$?
- Very difficult, if not impossible with fixed effects models.
 - · Complicated by the effect of treatment on time-varying confounders.
 - Pathways involving $\mathbf{X}_{it}(d_{t-1})$ difficult to identify.
- Possible approach: propensity score FEs (Blackwell & Yamauchi, 2021)

- Focused on the contemporaneous effect of D_{it} .
- What about treatment histories $Y_{it}(d_{t-1}, d_t)$?
- Very difficult, if not impossible with fixed effects models.
 - · Complicated by the effect of treatment on time-varying confounders.
 - + Pathways involving $\mathbf{X}_{it}(d_{t-1})$ difficult to identify.
- Possible approach: propensity score FEs (Blackwell & Yamauchi, 2021)
 - · Include unit dummies in propensity score model.

- Focused on the contemporaneous effect of D_{it} .
- What about treatment histories $Y_{it}(d_{t-1}, d_t)$?
- Very difficult, if not impossible with fixed effects models.
 - · Complicated by the effect of treatment on time-varying confounders.
 - Pathways involving $\mathbf{X}_{it}(d_{t-1})$ difficult to identify.
- Possible approach: propensity score FEs (Blackwell & Yamauchi, 2021)
 - Include unit dummies in propensity score model.
 - Bias from incidental parameters, but disappears as ${\it T} \rightarrow \infty$

3/ Synthetic control methods

• Abadie and Gardeazabal (2003) use a DID approach for "quantitative case studies."

- Abadie and Gardeazabal (2003) use a DID approach for "quantitative case studies."
- Application: effect of an intervention in a single country/state at one point in time.

- Abadie and Gardeazabal (2003) use a DID approach for "quantitative case studies."
- Application: effect of an intervention in a single country/state at one point in time.
- Basic idea: 1 treated group, many controls.

- Abadie and Gardeazabal (2003) use a DID approach for "quantitative case studies."
- Application: effect of an intervention in a single country/state at one point in time.
- Basic idea: 1 treated group, many controls.
 - · Compare the time-series outcomes in the treated group to the control.

- Abadie and Gardeazabal (2003) use a DID approach for "quantitative case studies."
- Application: effect of an intervention in a single country/state at one point in time.
- Basic idea: 1 treated group, many controls.
 - · Compare the time-series outcomes in the treated group to the control.
 - But which control group should you use?

- Abadie and Gardeazabal (2003) use a DID approach for "quantitative case studies."
- Application: effect of an intervention in a single country/state at one point in time.
- Basic idea: 1 treated group, many controls.
 - · Compare the time-series outcomes in the treated group to the control.
 - But which control group should you use?
 - Many possible choices and they may not be comparable to the treated.

- Abadie and Gardeazabal (2003) use a DID approach for "quantitative case studies."
- Application: effect of an intervention in a single country/state at one point in time.
- Basic idea: 1 treated group, many controls.
 - · Compare the time-series outcomes in the treated group to the control.
 - But which control group should you use?
 - Many possible choices and they may not be comparable to the treated.
- **Synthetic control**: use a convex combination of the controls to create a synthetic control.

- Abadie and Gardeazabal (2003) use a DID approach for "quantitative case studies."
- Application: effect of an intervention in a single country/state at one point in time.
- Basic idea: 1 treated group, many controls.
 - · Compare the time-series outcomes in the treated group to the control.
 - But which control group should you use?
 - Many possible choices and they may not be comparable to the treated.
- **Synthetic control**: use a convex combination of the controls to create a synthetic control.
 - Choose the weights that minimize the pretreatment differences between treated and synthetic control.

			Т	ime p	period		
	1	2		T_0	$T_{0} + 1$		Т
Treated unit $(i = 1)$	0	0	0	0	1	1	1
Control group $(i = 2, \dots, J + 1)$	0	0	0	0	0	0	0

• Treatment:

			Т	ime p	period		
	1	2		T_0	$T_{0} + 1$		Т
Treated unit $(i = 1)$	0	0	0	0	1	1	1
Control group $(i = 2, \dots, J + 1)$	0	0	0	0	0	0	0

- Treatment:
 - All units untreated for T_0 periods.

			Т	ime p	period		
	1	2		T_0	$T_{0} + 1$		Т
Treated unit $(i = 1)$	0	0	0	0	1	1	1
Control group $(i = 2, \dots, J + 1)$	0	0	0	0	0	0	0

- Treatment:
 - All units untreated for T_0 periods.
 - Unit 1 starts treatment at T_0 , continues until T.

			Т	ime p	period		
	1	2		T_0	$T_{0} + 1$		Т
Treated unit $(i = 1)$	0	0	0	0	1	1	1
Control group $(i = 2, \dots, J + 1)$	0	0	0	0	0	0	0

- Treatment:
 - All units untreated for T_0 periods.
 - Unit 1 starts treatment at T_0 , continues until T.
- Potential outcomes:

	Time period						
	1	2		T_0	$T_{0} + 1$		Т
Treated unit $(i = 1)$	0	0	0	0	1	1	1
Control group $(i = 2, \dots, J + 1)$	0	0	0	0	0	0	0

- Treatment:
 - All units untreated for T_0 periods.
 - Unit 1 starts treatment at T_0 , continues until T.
- Potential outcomes:
 - $Y_{it}(1)$: potential outcome at time t if i had been in the treated group.

	Time period						
	1	2		T_0	$T_{0} + 1$		Т
Treated unit $(i = 1)$	0	0	0	0	1	1	1
Control group $(i = 2, \dots, J + 1)$	0	0	0	0	0	0	0

- Treatment:
 - All units untreated for T_0 periods.
 - Unit 1 starts treatment at T_0 , continues until T.
- Potential outcomes:
 - $Y_{it}(1)$: potential outcome at time t if i had been in the treated group.
 - $Y_{it}(0)$: potential outcome at time t if i had been in the control group.

			Т	ime p	period		
	1	2		T_0	$T_{0} + 1$		Т
Treated unit $(i = 1)$	0	0	0	0	1	1	1
Control group $(i = 2, \dots, J + 1)$	0	0	0	0	0	0	0

- Treatment:
 - All units untreated for T_0 periods.
 - Unit 1 starts treatment at T_0 , continues until T.
- Potential outcomes:
 - $Y_{it}(1)$: potential outcome at time t if i had been in the treated group.
 - $Y_{it}(0)$: potential outcome at time t if i had been in the control group.
 - No pre-intervention impacts: $Y_{it}(1) = Y_{it}(0)$ for all $t \leq T_0$.

	Time period						
	1	2		T_0	$T_{0} + 1$		Т
Treated unit $(i = 1)$	0	0	0	0	1	1	1
Control group $(i = 2, \dots, J + 1)$	0	0	0	0	0	0	0

- Treatment:
 - All units untreated for T_0 periods.
 - Unit 1 starts treatment at T_0 , continues until T.
- Potential outcomes:
 - $Y_{it}(1)$: potential outcome at time t if i had been in the treated group.
 - $Y_{it}(0)$: potential outcome at time t if i had been in the control group.
 - No pre-intervention impacts: $Y_{it}(1) = Y_{it}(0)$ for all $t \leq T_0$.
- \mathbf{X}_i is an $r \times 1$ vector of (pretreatment) covariates.

	Time period						
	1	2		T_0	$T_{0} + 1$		Т
Treated unit $(i = 1)$	0	0	0	0	1	1	1
Control group $(i = 2, \dots, J + 1)$	0	0	0	0	0	0	0

- Treatment:
 - All units untreated for T_0 periods.
 - Unit 1 starts treatment at T_0 , continues until T.
- Potential outcomes:
 - $Y_{it}(1)$: potential outcome at time t if i had been in the treated group.
 - $Y_{it}(0)$: potential outcome at time t if i had been in the control group.
 - No pre-intervention impacts: $Y_{it}(1) = Y_{it}(0)$ for all $t \leq T_0$.
- \mathbf{X}_i is an $r \times 1$ vector of (pretreatment) covariates.
- Treatment effects: $\tau_{it} = Y_{it}(1) Y_{it}(0)$

			Т	ime p	period		
	1	2		T_0	$T_{0} + 1$		Т
Treated unit $(i = 1)$	0	0	0	0	1	1	1
Control group $(i = 2, \dots, J + 1)$	0	0	0	0	0	0	0

- Treatment:
 - All units untreated for T_0 periods.
 - Unit 1 starts treatment at T_0 , continues until T.
- Potential outcomes:
 - $Y_{it}(1)$: potential outcome at time t if i had been in the treated group.
 - $Y_{it}(0)$: potential outcome at time t if i had been in the control group.
 - No pre-intervention impacts: $Y_{it}(1) = Y_{it}(0)$ for all $t \leq T_0$.
- \mathbf{X}_i is an $r \times 1$ vector of (pretreatment) covariates.
- Treatment effects: $\tau_{it} = \mathit{Y}_{it}(1) \mathit{Y}_{it}(0)$
- Goal: estimate $\left(\tau_{1,T_{0}+1},\ldots,\tau_{1,T}\right)$.

Missing counterfactuals

• By consistency, for $t > T_0$:

$$\tau_{1t} = Y_{1t}(1) - Y_{1t}(0) = Y_{1t} - Y_{1t}(0)$$

Missing counterfactuals

• By consistency, for $t > T_0$:

$$\tau_{1t} = Y_{1t}(1) - Y_{1t}(0) = Y_{1t} - Y_{1t}(0)$$

• Need to impute missing potential outcomes, $Y_{1t}(0)$.
• By consistency, for $t > T_0$:

$$\tau_{1t} = Y_{1t}(1) - Y_{1t}(0) = Y_{1t} - Y_{1t}(0)$$

- Need to impute missing potential outcomes, $Y_{1t}(0)$.
- **Synthetic control**: Choose weights $(w_2, ..., w_{J+1})'$ such that:

• By consistency, for $t > T_0$:

$$\tau_{1t} = Y_{1t}(1) - Y_{1t}(0) = Y_{1t} - Y_{1t}(0)$$

- Need to impute missing potential outcomes, $Y_{1t}(0)$.
- **Synthetic control**: Choose weights $(w_2, ..., w_{J+1})'$ such that:

•
$$w_j \ge 0$$
 and $\sum_j w_j = 1$.

• By consistency, for $t > T_0$:

$$\tau_{1t} = Y_{1t}(1) - Y_{1t}(0) = Y_{1t} - Y_{1t}(0)$$

- Need to impute missing potential outcomes, $Y_{1t}(0)$.
- **Synthetic control**: Choose weights $(w_2, ..., w_{J+1})'$ such that:

•
$$w_j \ge 0$$
 and $\sum_j w_j = 1$.

• for all $t \leq T_0$ minimize

$$\left| Y_{1t} - \sum_{j=2}^{J+1} w_j Y_{jt} \right|, \qquad \left| \mathbf{Z}_1 - \sum_{j=2}^{J+1} w_j \mathbf{Z}_j \right|$$

• By consistency, for $t > T_0$:

$$\tau_{1t} = Y_{1t}(1) - Y_{1t}(0) = Y_{1t} - Y_{1t}(0)$$

- Need to impute missing potential outcomes, $Y_{1t}(0)$.
- **Synthetic control**: Choose weights $(w_2, ..., w_{J+1})'$ such that:

•
$$w_j \ge 0$$
 and $\sum_j w_j = 1$.

• for all $t \leq T_0$ minimize

$$\left| \mathbf{Y}_{1t} - \sum_{j=2}^{J+1} w_j \mathbf{Y}_{jt} \right|, \qquad \left| \mathbf{Z}_1 - \sum_{j=2}^{J+1} w_j \mathbf{Z}_j \right|$$

• Can also add a penalty for how dispersed the weights are.

• By consistency, for $t > T_0$:

$$\tau_{1t} = Y_{1t}(1) - Y_{1t}(0) = Y_{1t} - Y_{1t}(0)$$

- Need to impute missing potential outcomes, $Y_{1t}(0)$.
- **Synthetic control**: Choose weights $(w_2, ..., w_{J+1})'$ such that:

•
$$w_j \ge 0$$
 and $\sum_j w_j = 1$.

• for all $t \leq T_0$ minimize

$$\left| \mathbf{Y}_{1t} - \sum_{j=2}^{J+1} w_j \mathbf{Y}_{jt} \right|, \qquad \left| \mathbf{Z}_1 - \sum_{j=2}^{J+1} w_j \mathbf{Z}_j \right|$$

- · Can also add a penalty for how dispersed the weights are.
- We hope this implies for $t > T_0$: $\sum_{j=2}^{J+1} w_j Y_{jt} \approx Y_{1t}(0)$

Without synthetic controls



Figure 1. Trends in per-capita cigarette sales: California vs. the rest of the United States.

With synthetic controls



Figure 2. Trends in per-capita cigarette sales: California vs. synthetic California.

Weights

State	Weight	State	Weight
Alabama	0	Montana	0.199
Alaska	_	Nebraska	0
Arizona	_	Nevada	0.234
Arkansas	0	New Hampshire	0
Colorado	0.164	New Jersey	-
Connecticut	0.069	New Mexico	0
Delaware	0	New York	-
District of Columbia	_	North Carolina	0
Florida	-	North Dakota	0
Georgia	0	Ohio	0
Hawaii	_	Oklahoma	0
Idaho	0	Oregon	-
Illinois	0	Pennsylvania	0
Indiana	0	Rhode Island	0
Iowa	0	South Carolina	0
Kansas	0	South Dakota	0
Kentucky	0	Tennessee	0
Louisiana	0	Texas	0
Maine	0	Utah	0.334
Maryland	-	Vermont	0
Massachusetts	-	Virginia	0
Michigan	_	Washington	-
Minnesota	0	West Virginia	0
Mississippi	0	Wisconsin	0
Missouri	0	Wyoming	0

Inference



Figure 6. Per-capita cigarette sales gaps in California and placebo gaps in 29 control states (discards states with pre-Proposition 99 MSPE five times higher than California's).

• ADH provide two **model-based** justifications for SC.

- ADH provide two model-based justifications for SC.
- Model 1: Interacted factor model

- ADH provide two model-based justifications for SC.
- Model 1: Interacted factor model

 $Y_{it}(0) = \mathbf{X}_i' \boldsymbol{\beta}_t + \boldsymbol{\alpha}_i + \boldsymbol{\delta}_t + \boldsymbol{\lambda}_t \boldsymbol{\mu}_i + \boldsymbol{\varepsilon}_{it}$

• $\boldsymbol{\beta}_t$ are time-varying coefficients on covariates.

- ADH provide two model-based justifications for SC.
- Model 1: Interacted factor model

- $\boldsymbol{\beta}_t$ are time-varying coefficients on covariates.
- $\boldsymbol{\lambda}_t$ is a 1 imes *F* vector of common factors

- ADH provide two model-based justifications for SC.
- Model 1: Interacted factor model

- $\boldsymbol{\beta}_t$ are time-varying coefficients on covariates.
- $\boldsymbol{\lambda}_t$ is a 1 imes *F* vector of common factors
- $\boldsymbol{\mu}_i$ is a $F \times 1$ vector of factor loadings

- ADH provide two model-based justifications for SC.
- Model 1: Interacted factor model

- $\boldsymbol{\beta}_t$ are time-varying coefficients on covariates.
- $\boldsymbol{\lambda}_t$ is a 1 imes *F* vector of common factors
- $\boldsymbol{\mu}_i$ is a $F \times 1$ vector of factor loadings
- $\boldsymbol{\lambda}_t \boldsymbol{\mu}_i$ allows time-varying confounding in a structured way.

- ADH provide two model-based justifications for SC.
- Model 1: Interacted factor model

- $\boldsymbol{\beta}_t$ are time-varying coefficients on covariates.
- $\boldsymbol{\lambda}_t$ is a 1 imes *F* vector of common factors
- $\boldsymbol{\mu}_i$ is a $F \times 1$ vector of factor loadings
- $\boldsymbol{\lambda}_t \boldsymbol{\mu}_i$ allows time-varying confounding in a structured way.
- Common time shocks affect each unit in a time-constant way.

- ADH provide two model-based justifications for SC.
- Model 1: Interacted factor model

- $\boldsymbol{\beta}_t$ are time-varying coefficients on covariates.
- $\boldsymbol{\lambda}_t$ is a 1 imes *F* vector of common factors
- $\boldsymbol{\mu}_i$ is a $F \times 1$ vector of factor loadings
- $\lambda_t \mu_i$ allows time-varying confounding in a structured way.
- Common time shocks affect each unit in a time-constant way.
- Model 2: autoregressive model without fixed effects

$$\begin{aligned} Y_{i,t+1}(0) &= \alpha_t Y_{it}(0) + \boldsymbol{\beta}_{t+1} \mathbf{X}_{i,t+1} + u_{i,t+1} \\ \mathbf{X}_{i,t+1} &= \gamma_t Y_{it}(0) + \mathbf{\Pi}_t \mathbf{X}_{it} + \mathbf{v}_{i,t+1} \end{aligned}$$

- ADH provide two model-based justifications for SC.
- Model 1: Interacted factor model

 $Y_{it}(0) = \mathbf{X}_i' \boldsymbol{\beta}_t + \boldsymbol{\alpha}_i + \boldsymbol{\delta}_t + \boldsymbol{\lambda}_t \boldsymbol{\mu}_i + \boldsymbol{\varepsilon}_{it}$

- $\boldsymbol{\beta}_t$ are time-varying coefficients on covariates.
- $\boldsymbol{\lambda}_t$ is a 1 imes *F* vector of common factors
- $\boldsymbol{\mu}_i$ is a $F \times 1$ vector of factor loadings
- $\lambda_t \mu_i$ allows time-varying confounding in a structured way.
- Common time shocks affect each unit in a time-constant way.
- Model 2: autoregressive model without fixed effects

$$\begin{aligned} Y_{i,t+1}(0) &= \alpha_t Y_{it}(0) + \boldsymbol{\beta}_{t+1} \mathbf{X}_{i,t+1} + u_{i,t+1} \\ \mathbf{X}_{i,t+1} &= \gamma_t Y_{it}(0) + \mathbf{\Pi}_t \mathbf{X}_{it} + \mathbf{v}_{i,t+1} \end{aligned}$$

• Either fixed effects OR lagged dependent variables, not both.

• Suppose perfect balancing weights exist $(w_2^*, \dots, w_{J+1}^*)$ such that:

$$\sum_{j=2}^{J+1} w_j^* Y_{jt} = Y_{1t} \qquad \sum_{j=2}^{J+1} w_j^* \mathbf{X}_j = \mathbf{X}_i$$

• Suppose perfect balancing weights exist $(w_2^*, \dots, w_{J+1}^*)$ such that:

$$\sum_{j=2}^{J+1} w_j^* Y_{jt} = Y_{1t}$$
 $\sum_{j=2}^{J+1} w_j^* \mathbf{X}_j = \mathbf{X}_j$

• Suppose perfect balancing weights exist $(w_2^*, \dots, w_{J+1}^*)$ such that:

$$\sum_{j=2}^{J+1} w_j^* Y_{jt} = Y_{1t}$$
 $\sum_{j=2}^{J+1} w_j^* X_j = X_j$

• Let $\widehat{Y}_{1t}(0) = \sum_{j=2}^{J+1} w_j^* Y_{jt}$ for post-intervention periods.

- Under Model 1, $\widehat{Y}_{1t}(0)
ightarrow Y_{1t}(0)$ as $T_0
ightarrow \infty$

• Suppose perfect balancing weights exist $(w_2^*, \dots, w_{J+1}^*)$ such that:

$$\sum_{j=2}^{J+1} w_j^* Y_{jt} = Y_{1t}$$
 $\sum_{j=2}^{J+1} w_j^* \mathbf{X}_j = \mathbf{X}_j$

- Under Model 1, $\widehat{Y}_{1t}(0)
 ightarrow Y_{1t}(0)$ as $T_0
 ightarrow \infty$
 - As length of pre-intervention period grows, estimates get better.

• Suppose perfect balancing weights exist $(w_2^*, \dots, w_{J+1}^*)$ such that:

$$\sum_{j=2}^{J+1} w_j^* Y_{jt} = Y_{1t}$$
 $\sum_{j=2}^{J+1} w_j^* \mathbf{X}_j = \mathbf{X}_j$

- Under Model 1, $\widehat{Y}_{1t}(0)
 ightarrow Y_{1t}(0)$ as $T_0
 ightarrow \infty$
 - As length of pre-intervention period grows, estimates get better.
- Under Model 2, $\mathbb{E}\left[\widehat{Y}_{1t}(0)\right] = \mathbb{E}[Y_{1t}(0)]$

• Suppose perfect balancing weights exist $(w_2^*, \dots, w_{J+1}^*)$ such that:

$$\sum_{j=2}^{J+1} w_j^* Y_{jt} = Y_{1t}$$
 $\sum_{j=2}^{J+1} w_j^* \mathbf{X}_j = \mathbf{X}_j$

- Under Model 1, $\widehat{Y}_{1t}(0)
 ightarrow Y_{1t}(0)$ as $T_0
 ightarrow \infty$
 - As length of pre-intervention period grows, estimates get better.
- Under Model 2, $\mathbb{E}\left[\widehat{Y}_{1t}(0)\right] = \mathbb{E}[Y_{1t}(0)]$
 - Unbiased only based on one pre-treatment periods.

• Suppose perfect balancing weights exist $(w_2^*, \dots, w_{J+1}^*)$ such that:

$$\sum_{j=2}^{J+1} w_j^* Y_{jt} = Y_{1t}$$
 $\sum_{j=2}^{J+1} w_j^* \mathbf{X}_j = \mathbf{X}_j$

- Under Model 1, $\widehat{Y}_{1t}(0) o Y_{1t}(0)$ as $T_0 o \infty$
 - As length of pre-intervention period grows, estimates get better.
- Under Model 2, $\mathbb{E}\left[\widehat{Y}_{1t}(0)\right] = \mathbb{E}[Y_{1t}(0)]$
 - Unbiased only based on one pre-treatment periods.
 - But it assumes away unmeasured confounding!

• Suppose perfect balancing weights exist $(w_2^*, \dots, w_{J+1}^*)$ such that:

$$\sum_{j=2}^{J+1} w_j^* Y_{jt} = Y_{1t}$$
 $\sum_{j=2}^{J+1} w_j^* \mathbf{X}_j = \mathbf{X}_j$

- Under Model 1, $\widehat{Y}_{1t}(0) o Y_{1t}(0)$ as $T_0 o \infty$
 - As length of pre-intervention period grows, estimates get better.
- Under Model 2, $\mathbb{E}\left[\widehat{Y}_{1t}(0)\right] = \mathbb{E}[Y_{1t}(0)]$
 - Unbiased only based on one pre-treatment periods.
 - But it assumes away unmeasured confounding!
- Outside of those models: ????

- When pre-treatment fit is imperfect \rightsquigarrow significant bias in SCM

- When pre-treatment fit is imperfect \rightsquigarrow significant bias in SCM
- Augmented SCM: use regression models to correct for bias

- When pre-treatment fit is imperfect \rightsquigarrow significant bias in SCM
- · Augmented SCM: use regression models to correct for bias
 - Let $\widehat{m}_{it} = \widehat{m}_{it}(\overline{Y}_{i,t-1})$ be predicted values for a regression of post-treatment outcomes on pre-treatment outcomes.

- When pre-treatment fit is imperfect \rightsquigarrow significant bias in SCM
- · Augmented SCM: use regression models to correct for bias
 - Let $\widehat{m}_{it} = \widehat{m}_{it}(\overline{Y}_{i,t-1})$ be predicted values for a regression of post-treatment outcomes on pre-treatment outcomes.
 - Augment estimator (Ben-Michael, et al, 2021, JASA):

$$\widehat{Y}_{1t}^{\text{aug}}(0) = \sum_{j=2}^{J+1} w_j Y_{jt} + \left(\widehat{m}_{1t} - \sum_{j=2}^{J+1} w_j \widehat{m}_{jt}\right)$$

- When pre-treatment fit is imperfect \rightsquigarrow significant bias in SCM
- · Augmented SCM: use regression models to correct for bias
 - Let $\widehat{m}_{it} = \widehat{m}_{it}(\overline{Y}_{i,t-1})$ be predicted values for a regression of post-treatment outcomes on pre-treatment outcomes.
 - Augment estimator (Ben-Michael, et al, 2021, JASA):

$$\widehat{Y}_{1t}^{\text{aug}}(\mathbf{0}) = \sum_{j=2}^{J+1} w_j Y_{jt} + \left(\widehat{m}_{1t} - \sum_{j=2}^{J+1} w_j \widehat{m}_{jt}\right)$$

• Can add covariates fairly easily.

- When pre-treatment fit is imperfect \rightsquigarrow significant bias in SCM
- · Augmented SCM: use regression models to correct for bias
 - Let $\widehat{m}_{it} = \widehat{m}_{it}(\overline{Y}_{i,t-1})$ be predicted values for a regression of post-treatment outcomes on pre-treatment outcomes.
 - Augment estimator (Ben-Michael, et al, 2021, JASA):

$$\widehat{Y}_{1t}^{\text{aug}}(\mathbf{0}) = \sum_{j=2}^{J+1} w_j Y_{jt} + \left(\widehat{m}_{1t} - \sum_{j=2}^{J+1} w_j \widehat{m}_{jt}\right)$$

- Can add covariates fairly easily.
- Very similar to bias correction in matching.

• Two estimation methods to generalize to any number of treated units.

- Two estimation methods to generalize to any number of treated units.
- Interactive fixed effects: $Y_{it}(0) = \mathbf{X}'_{it}\boldsymbol{\beta} + \alpha_i + \delta_t + \boldsymbol{\lambda}_t \boldsymbol{\mu}_i$

- Two estimation methods to generalize to any number of treated units.
- Interactive fixed effects: $Y_{it}(0) = \mathbf{X}'_{it}\boldsymbol{\beta} + \alpha_i + \delta_t + \boldsymbol{\lambda}_t \boldsymbol{\mu}_i$
 - Instead of weights, directly estimate IFE using iterative procedure:

- Two estimation methods to generalize to any number of treated units.
- Interactive fixed effects: $Y_{it}(0) = \mathbf{X}'_{it}\boldsymbol{\beta} + \alpha_i + \delta_t + \boldsymbol{\lambda}_t \boldsymbol{\mu}_i$
 - Instead of weights, directly estimate IFE using iterative procedure:
 - 1. Treat IFE terms as fixed and fit parametric part on untreated units to get new $\hat{\beta}$
- Two estimation methods to generalize to any number of treated units.
- Interactive fixed effects: $Y_{it}(0) = \mathbf{X}'_{it}\boldsymbol{\beta} + \alpha_i + \delta_t + \boldsymbol{\lambda}_t \boldsymbol{\mu}_i$
 - Instead of weights, directly estimate IFE using iterative procedure:
 - 1. Treat IFE terms as fixed and fit parametric part on untreated units to get ${\rm new}\,\hat{\beta}$
 - Treat covariate coefficients as fixed and use factor analysis to estimate IFE terms.

- Two estimation methods to generalize to any number of treated units.
- Interactive fixed effects: $Y_{it}(0) = \mathbf{X}'_{it}\boldsymbol{\beta} + \alpha_i + \delta_t + \boldsymbol{\lambda}_t \boldsymbol{\mu}_i$
 - Instead of weights, directly estimate IFE using iterative procedure:
 - 1. Treat IFE terms as fixed and fit parametric part on untreated units to get $\mathrm{new}\,\hat{\beta}$
 - Treat covariate coefficients as fixed and use factor analysis to estimate IFE terms.
 - 3. Repeat until convergence.

- Two estimation methods to generalize to any number of treated units.
- Interactive fixed effects: $Y_{it}(0) = \mathbf{X}'_{it}\boldsymbol{\beta} + \alpha_i + \delta_t + \boldsymbol{\lambda}_t \boldsymbol{\mu}_i$
 - Instead of weights, directly estimate IFE using iterative procedure:
 - 1. Treat IFE terms as fixed and fit parametric part on untreated units to get new $\hat{\beta}$
 - 2. Treat covariate coefficients as fixed and use factor analysis to estimate IFE terms.
 - 3. Repeat until convergence.
- Matrix completion methods (Athey et al, 2021)

- Two estimation methods to generalize to any number of treated units.
- Interactive fixed effects: $Y_{it}(0) = \mathbf{X}'_{it}\boldsymbol{\beta} + \alpha_i + \delta_t + \boldsymbol{\lambda}_t \boldsymbol{\mu}_i$
 - Instead of weights, directly estimate IFE using iterative procedure:
 - 1. Treat IFE terms as fixed and fit parametric part on untreated units to get new $\hat{\beta}$
 - 2. Treat covariate coefficients as fixed and use factor analysis to estimate IFE terms.
 - 3. Repeat until convergence.
- Matrix completion methods (Athey et al, 2021)
 - Treat matrix of control POs, $\mathbf{Y}(\mathbf{0})$ as missing data problem.

- Two estimation methods to generalize to any number of treated units.
- Interactive fixed effects: $Y_{it}(0) = \mathbf{X}'_{it}\boldsymbol{\beta} + \alpha_i + \delta_t + \boldsymbol{\lambda}_t \boldsymbol{\mu}_i$
 - Instead of weights, directly estimate IFE using iterative procedure:
 - 1. Treat IFE terms as fixed and fit parametric part on untreated units to get new $\hat{\beta}$
 - 2. Treat covariate coefficients as fixed and use factor analysis to estimate IFE terms.
 - 3. Repeat until convergence.
- Matrix completion methods (Athey et al, 2021)
 - Treat matrix of control POs, $\mathbf{Y}(\mathbf{0})$ as missing data problem.
 - Estimate lower-rank matrix ${\bf L}$ as best approximation to observed parts of ${\bf Y}({\bf 0})$ subject to regularization.