# **Module 9: Panel Data**

Fall 2021

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Gov 2003 (Harvard)

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- Now there are two possible sources of variation to exploit:
	- Exploit **cross-sectional** variation in treatment.
	- Exploit variation in treatment **within a unit over time** (before/after)

#### **Cross-sectional vs before/after**



## **1/** Difference in differences

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Time period Pre-period  $(t = 0)$  Post-period  $(t = 1)$ Control group  $(G_i = 0)$   $D_{i0} = 0$   $D_{i1} = 0$ Treated group  $(G_i = 1)$   $D_{i0} = 0$   $D_{i1} = 1$ 

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$$
\tau_{ATT}=\mathbb{E}[Y_{i1}(1)-Y_{i1}(0)|G_i=1]
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• Part (a) is just a conditional average of observed data  $\rightsquigarrow$  identified.

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- Part (a) is just a conditional average of observed data  $\rightsquigarrow$  identified.
- Part (b) is a counterfactual: what would the average outcome in the treated group have been if it have been in control?

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- **Cross-sectional design**
	- Assumption: mean independence of treatment

$$
\mathbb{E}[Y_{i1}(0)|G_i = 1] = \mathbb{E}[Y_{i1}(0)|G_i = 0]
$$

• Use post-treatment control group:

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- **Before-and-after design**
	- Assumption: no trends

$$
\mathbb{E}[Y_{i1}(0)|G_i = 1] = \mathbb{E}[Y_{i0}(0)|G_i = 1]
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• Use pre-period outcome in treated group:

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- **Difference-in-differences**:
	- Assumption: parallel trends

$$
\mathbb{E}[Y_{i1}(0) - Y_{i0}(0)|G_i = 0] = \mathbb{E}[Y_{i1}(0) - Y_{i0}(0)|G_i = 1]
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• Use pre-period treated outcome plus trend in control group:

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- Not invariant to nonlinear transformations!
	- Parallel trends for  $Y_{i}$  implies non-parallel trends for log( $Y_{i}$ ) and vice versa.

# **Parallel trends in a graph**



## **Parallel trends in a graph**



# **Identification**

$$
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- Falsification test: check pre-treatment parallel trends.

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	- **Ashenfelter's dip**: empirical finding that people who enroll in job training programs see their earnings decline prior to that training.
- Falsification test: check pre-treatment parallel trends.
	- Doesn't imply parallel trends hold for the post-period however!

# **Checking parallel trends (de Kadt/Larreguy, 2018)**



• Estimation with panel data:

$$
\widehat{\tau}_{\text{ATT}} = \underbrace{\frac{1}{n_1} \sum_{i=1}^{n} G_i \{ Y_{i1} - Y_{i0} \}}_{\text{max}} - \underbrace{\frac{1}{n_0} \sum_{i=1}^{n} (1 - G_i) \{ Y_{i1} - Y_{i0} \}}_{\text{max}}
$$

average trend in treated group

average trend in the control group

• Estimation with panel data:

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\widehat{\tau}_{\text{ATT}} = \underbrace{\frac{1}{n_1}\sum_{i=1}^n G_i\left\{Y_{i1} - Y_{i0}\right\}}_{\text{average trend in treated group}} - \underbrace{\frac{1}{n_0}\sum_{i=1}^n (1-G_i)\left\{Y_{i1} - Y_{i0}\right\}}_{\text{average trend in the control group}}
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• Standard errors from standard difference in means.

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	- Use (cluster) robust SEs
- Also possible to use DID on repeated cross sections.

### **DID and linear two-way fixed effects**

• Linear two-way (group and time) fixed effect model:

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- Coefficient on  $D_{it}$  equivalent to DID estimation.

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- Coefficient on  $D_{it}$  equivalent to DID estimation.
- Only holds for the 2 group, 2 period case!
	- Large new literature on interpretation of TWFE in more general cases.
	- Basically, TWFE is an odd weighted average of DID effects with sometimes negative weights.

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 $Y_{i1}(0) \perp \!\!\! \perp G_i \mid Y_{i0}$ 

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- Different ideas about why there is imbalance on the LDV:
	- DID: time-constant unmeasured confounder creates imbalance.

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- Doesn't imply and isn't implied by parallel trends.
- Benefit over parallel trends: it is scale-free.
- Equivalent to parallel trends if  $\mathbb{E}[Y_{i0} | G_i = 1] = \mathbb{E}[Y_{i0} | G_i = 0]$
- Different ideas about why there is imbalance on the LDV:
	- DID: time-constant unmeasured confounder creates imbalance.
	- LDV: previous outcome directly affects treatment assignment.

• Estimator: estimate CEF  $\mathbb{E}[Y_{i1} | Y_{i0}, G_i] = \alpha + \rho Y_{i0} + \tau G_i$ 

$$
\widehat{\tau}_{LDV} = \underbrace{\frac{1}{n_1} \sum_{i=1}^{n} G_i Y_{i1} - \frac{1}{n_0} \sum_{i=1}^{n} (1 - G_i) Y_{i1}}_{\text{difference in post period}}
$$
\n
$$
- \widehat{\rho}_{LDV} \underbrace{\left\{ \frac{1}{n_1} \sum_{i=1}^{n} G_i Y_{i0} - \frac{1}{n_0} \sum_{i=1}^{n} (1 - G_i) Y_{i0} \right\}}_{\text{max}} \right\}
$$

difference in pre period

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$$
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$$

• If 
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\hat{\rho}_{LDV} = 1
$$
 then  $\hat{\tau}_{DID} = \hat{\tau}_{LDV}$  and if  $0 \leq \hat{\rho}_{LDV} < 1$ :

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- **Matching**: conduct DID analysis on units with similar values of **X**

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	- Possible model misspecification!

# **2/** Fixed effects

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# **Strict exogeneity DAG**



Strict exogeneity implied by strict ignorability  $Y_{it}(d) \perp\!\!\!\perp D_i \mid X_i, U_i$ 

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	- FD more efficient if differences,  $\Delta \varepsilon_{i}$ , are serially uncorrelated.

- With linear models, two transformations can purge the fixed effects.
- Within/FE transformation:  $\ddot{Z}_{it} = Z_{it} \mathcal{T}^{-1} \sum_{s=1}^{T} Z_{is}$

$$
\ddot{Y}_{it} = \ddot{X}_{it}'\beta + \tau \ddot{D}_{it} + \ddot{\varepsilon}_{it}
$$

- Time-demeaning  $Y_{it}$  purges the time constant fixed effect.
- But they retain the same coefficients as the original model.
- **First differences**:  $\Delta Z_{it} = Z_{it} Z_{i,t-1}$

$$
\Delta Y_{it} = \Delta \mathbf{X}_{it}' \boldsymbol{\beta} + \tau \Delta D_{it} + \Delta \varepsilon_{it}
$$

- Estimation: pooled OLS of either specification,  $\widehat{\tau}_{\mathsf{f}\alpha}$ ,  $\widehat{\tau}_{\mathsf{f}d}$ 
	- Both consistent under strict exogeneity.
	- FE more efficient if original errors,  $\varepsilon_{it}$ , are serially uncorrelated.
	- FD more efficient if differences,  $\Delta \varepsilon_{i}$ , are serially uncorrelated.
	- Latter allows for substantial serial dependence in the original errors.

$$
\underset{\alpha,\beta,\tau,\gamma}{\arg\max} \sum_{i=1}^n \sum_{t=1}^T \left(Y_{it} - \alpha - \mathbf{X}_{it}'\beta - \tau D_{it} - \sum_{k=2}^n \gamma_k \mathbb{1}(i=k)\right)^2
$$

• Within estimator can be implemented by adding unit dummy variables.

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	- {fixest} in R, -reghdfe- in Stata

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	- {PanelMatch} R package.

# **Strict vs. sequential exogeneity/ignorability**

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	- bias correction: estimate the bias and subtract it off (valid for nonlinear models too).

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	- Bias from incidental parameters, but disappears as  $T \rightarrow \infty$

# **3/** Synthetic control methods

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- **Synthetic control**: use a convex combination of the controls to create a synthetic control.
	- Choose the weights that minimize the pretreatment differences between treated and synthetic control.



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- Treatment effects:  $\tau_{it} = Y_{it}(1) Y_{it}(0)$
- Goal: estimate  $(\tau_{1, \tau_{\alpha+1}}, \ldots, \tau_{1, \tau}).$

## **Missing counterfactuals**

• By consistency, for  $t > T_0$ :

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- Can also add a penalty for how dispersed the weights are.
- $\text{\textbf{•}}\,$  We hope this implies for  $t>T_0\text{: } \sum_{j=2}^{J+1} w_j Y_{jt} \approx Y_{1t}(0)$

#### **Without synthetic controls**



Figure 1. Trends in per-capita cigarette sales: California vs. the rest of the United States.

### **With synthetic controls**



Figure 2. Trends in per-capita cigarette sales: California vs. synthetic California.

# **Weights**



#### **Inference**



Figure 6. Per-capita cigarette sales gaps in California and placebo gaps in 29 control states (discards states with pre-Proposition 99 MSPE five times higher than California's).

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• Either fixed effects OR lagged dependent variables, not both.

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- Outside of those models: ?????

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- Very similar to bias correction in matching.

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	- $\cdot$  Estimate lower-rank matrix **L** as best approximation to observed parts of  $Y(0)$  subject to regularization.